# **OMRON**

### **RFID System**

# **V600 Series**

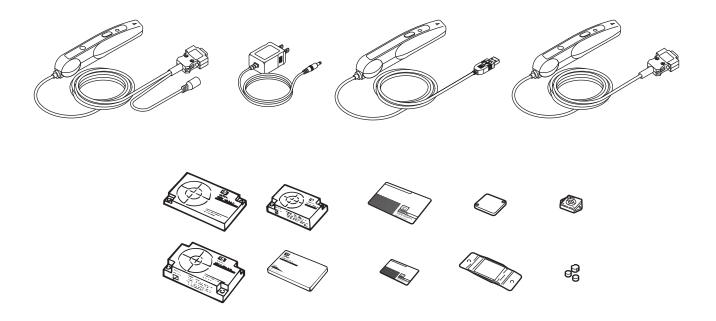
# **User's Manual**

Hand-held Reader Writer

V600-CHUD V600-CH1D-V2 V600-CH1D-PSI

**Data Carriers** 

V600 Series



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# **RFID System**

V600-CHUD Hand-held Reader Writer V600-CH1D-V2 Hand-held Reader Writer V600-CH1D-PSI Hand-held Reader Writer

V600 Series Data Carriers

# **User's Manual**

#### READ AND UNDERSTAND THIS DOCUMENT

Please read and understand this document before using the products. Please consult your OMRON representative if you have any questions or comments.

#### WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

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OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE, OR STRICT

In no event shall responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

IN NO EVENT SHALL OMRON BE RESPONSIBLE FOR WARRANTY, REPAIR, OR OTHER CLAIMS REGARDING THE PRODUCTS UNLESS OMRON'S ANALYSIS CONFIRMS THAT THE PRODUCTS WERE PROPERLY HANDLED, STORED, INSTALLED, AND MAINTAINED AND NOT SUBJECT TO CONTAMINATION, ABUSE, MISUSE, OR INAPPROPRIATE MODIFICATION OR REPAIR.

#### SUITABILITY FOR USE

THE PRODUCTS CONTAINED IN THIS DOCUMENT ARE NOT SAFETY RATED. THEY ARE NOT DESIGNED OR RATED FOR ENSURING SAFETY OF PERSONS, AND SHOULD NOT BE RELIED UPON AS A SAFETY COMPONENT OR PROTECTIVE DEVICE FOR SUCH PURPOSES. Please refer to separate catalogs for OMRON's safety rated products.

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the product.

At the customer's request, OMRON will provide applicable third party certification documents identifying ratings and limitations of use that apply to the products. This information by itself is not sufficient for a complete determination of the suitability of the products in combination with the end product, machine, system, or other application or use.

The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products:

Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this document.

Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety

- equipment, and installations subject to separate industry or government regulations.

   Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

#### PERFORMANCE DATA

Performance data given in this document is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

#### CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the product may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased

#### **DIMENSIONS AND WEIGHTS**

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

#### ERRORS AND OMISSIONS

The information in this document has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

#### **PROGRAMMABLE PRODUCTS**

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof.

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### **Meanings of Signal Words**

The following signal words are used in this manual.



Indicates a potentially hazardous situation which, if not avoided, will result in minor or moderate injury, or may result in serious injury or death. Additionally, there may be significant property damage.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.

### **Meanings of Alert Symbols**

The following alert symbols are used in this manual.



Indicates the possibility of explosion under specific conditions.



Indicates general prohibitions for which there is no specified symbol.

#### **Alert Statements in This Manual**

The following alert statements apply to the products in this manual. Each alert statement also appears at the locations needed in this manual to attract your attention.

### ✓ WARNING This product is not designed to be used either directly or indirectly in applications that detect human presence for the purpose of maintaining safety. Do not use this product as a sensing device for protecting human lives. A lithium battery is built into SRAM Data Carriers and may occasionally combust, explode, or burn if not treated properly. Dispose of SRAM Data Carriers as industrial waste and never disassemble, apply pressure that would deform, heat to higher than 100°C, or incinerate SRAM Data Carriers.

## **Precautions for Safe Use**

Observe the following precautions to ensure safe use of the product.

- 1. Do not use the product in environments with flammable, explosive, or corrosive gasses.
- 2. Do not attempt to disassemble, repair, or modify the product.
- 3. The USB driver must be installed in the personal computer before connecting the V600-CHUD to a personal computer.
- 4. Do not subject cables to excessive loads.
- 5. Observe all warnings and precautions given in the body of this manual.
- 6. Discontinue usage and turn OFF the power supply immediately if you notice any unusual odors, if the product is abnormally hot, or if the product starts smoking.
- 7. When disposing of the product, treat it as industrial waste.

### **Precautions for Correct Use**

Always observe the following precautions to prevent operation failures, malfunctions, and adverse effects on performance and equipment.

#### 1. Installation Environment

Install the product in the following locations:

- Locations not subject to corrosive gas, dust, metallic powder, or salt.
- Locations within the specified operating temperature range.
- Locations not subject to rapid changes in temperature (with no condensation).
- Locations within the specified humidity range.
- Locations not subject to direct vibration or shock outside the specified ranges.
- Locations not subject to water, oil, or chemicals.

#### 2. Installation

- The product communicates with Data Carriers using the 530-kHz frequency band. Some motors, inverters, switching power supplies, and other devices generate noise that can affect communications with the Data Carriers. If such devices are located near the Data Carriers, communications with the Data Carriers may be adversely affected or the Data Carriers may be destroyed. Whenever using the product near devices of this nature, always test operation in advance to confirm if the system will be affected.
- Observe the following precautions to minimize the effects of normal noise.
  - (1) Ground all metal objects in the vicinity to 100  $\Omega$  or less.
  - (2) Do not use the system near high-voltage or high-current lines.
- Connectors are not waterproof. Do not use the product where mists are present.
- Do not use chemicals that would affect the materials used in the product.
- Always be sure the USB connector is properly inserted when using the USB port.

#### 3. Cleaning

• Do not clean the product with thinners, benzene, or other organic solvents. These will dissolve the resin parts and coating on the case.

# **How to Read this Manual**

### **Meanings of Symbols**



Indicates particularly important points related to a function, including precautions and application advice.



Indicates page numbers containing relevant information.



Indicates reference to helpful information and explanations for difficult terminology.

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### Introduction

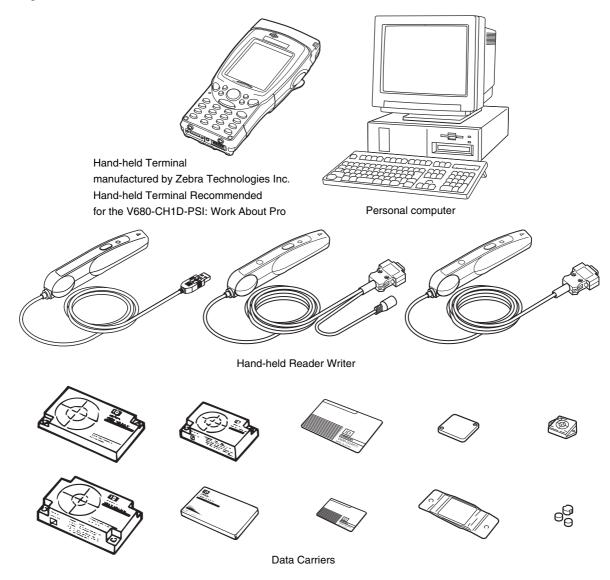
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# **Section 1 Product Overview**

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### **Features**

The V600-CHUD Hand-held Reader Writer incorporates a V600-series Antenna and Controller into a compact device conforming to USB 1.1. Data can be read from or written to the Data Carrier simply by approaching or touching the Data Carrier with the Hand-held Reader Writer.



#### V600-CHUD

This Hand-held Reader/Writer provides a USB connector that conforms to the USB 1.1 standard. Connecting the Hand-held Reader/Writer to a personal computer or Hand-held Terminal gives it superior portability, and operability.

#### V600-CH1D-V2

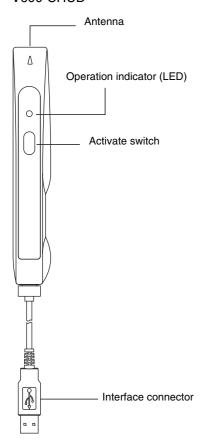
A built-in RS-232C interface allows this Hand-held Reader/Writer to be connected to a personal computer or programmable controller.

#### V600-CH1D-PSI

A built-in RS-232C interface allows this Hand-held Reader/Writer to be connected to a Hand-held Terminal, giving it superior portability, and operability.

# **Names and Functions of Components**

#### V600-CHUD



#### Operation Indicator (LED)

Display	Meaning
	A command has been received from the host device.
	Communications with the Data Carrier have completed normally.
	The execution result of the noise detection command (NS) is "A" (low noise).
Lit green	The result of the error noise detection command (EN) is "0" (normal).
$\bigcirc$	When the power is turned ON, after initialization of the Hand-held Reader Writer is completed
	Communications with the Data Carrier are in progress.
Flashing green	
	A communications error with the Data Carrier has occurred.
	A CPU error has occurred.
Lit red	The battery low warning (End code: 7B) has occurred.
	A Data Carrier non-existent error has occurred.
Flashing red	A communications error with the host device has occurred.
	The execution result of the noise detection command (NS) is "B" (high noise).
	The result of the error noise detection command (EN) is "1" (error).



After the operation indicator is lit or flashing for a certain time, it will turn OFF.

#### Activate Switch

When button commands (button commands, button auto commands) are used and the activate switch is pressed, communications with the Data Carrier will commence. (For details on button commands, refer to Section 3 Commands.)

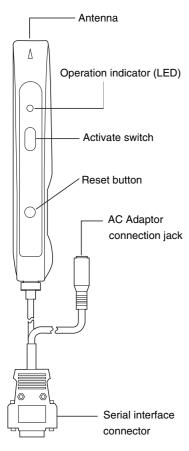
#### Interface Connector

This is a USB interface with an A-series plug based on USB 1.1.

#### Antenna

To communicate with the Data Carrier, move the antenna head closer to it.

#### V600-CH1D-V2



#### Operation Indicator (LED)

Display	Meaning
	A command has been received from the host device.
Lit green	Communications with the Data Carrier have completed normally.
	<ul> <li>When the power is turned ON, after initialization of the Handheld Reader Writer is completed</li> <li>When the power is turned ON and the reset button is pressed for two seconds or more (initialization stand-by mode).</li> </ul>
Flashing green	Communications with the Data Carrier are in progress.
	A communications error with the Data Carrier has occurred.
	A CPU error has occurred.
Lit red	The battery low warning (End code: 7B) has occurred.
	A Data Carrier non-existent error has occurred.
Flashing red	A communications error with the host device has occurred.



After the operation indicator is lit or flashing for a certain time, it will turn OFF.

#### Activate Switch

When button commands (button commands, button auto commands) are used and the activate switch is pressed, communications with the Data Carrier will commence. (For details on button commands, refer to Section 3 Commands.)

When the activate switch is pressed with the Hand-held Reader Writer in the initialization stand-by mode (with the green LED flashing) the function settings will be initialized.

#### Reset Button

Press this button for two seconds or more when the power is first turned ON to put the Hand-held Reader Writer into the initialization stand-by mode.

#### AC Adaptor Connection Jack

This is a connection jack for the V600-A22 AC.

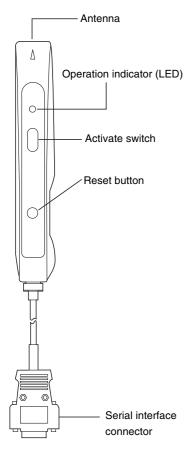
#### Serial Interface Connector

This is a serial interface with an RS-232C-compliant D-Sub 9-pin connector.

#### Antenna

To communicate with the Data Carrier, move the antenna head closer to it.

#### V600-CH1D-PSI



#### Operation Indicator (LED)

Display	Meaning
	A command has been received from the host device.
Lit green	Communications with the Data Carrier have completed normally.
	<ul> <li>When the power is turned ON, after initialization of the Handheld Reader Writer is completed</li> <li>When the power is turned ON and the reset button is pressed for two seconds or more (initialization stand-by mode).</li> </ul>
Flashing green	Communications with the Data Carrier are in progress.
	A communications error with the Data Carrier has occurred.
	A CPU error has occurred.
Lit red	The battery low warning (End code: 7B) has occurred.
	A Data Carrier non-existent error has occurred.
Flashing red	A communications error with the host device has occurred.



After the operation indicator is lit or flashing for a certain time, it will turn OFF.

#### Activate Switch

When button commands (button commands, button auto commands) are used and the activate switch is pressed, communications with the Data Carrier will commence. (For details on button commands, refer to Section 3 Commands.)

When the activate switch is pressed with the Hand-held Reader Writer in the initialization stand-by mode (with the green LED flashing) the function settings will be initialized.

#### Reset Button

Press this button for two seconds or more when the power is first turned ON to put the Hand-held Reader Writer into the initialization stand-by mode.

#### AC Adaptor Connection Jack

This is a connection jack for the V600-A22 AC.

#### Serial Interface Connector

This is a serial interface with an RS-232C-compliant D-Sub 9-pin connector.

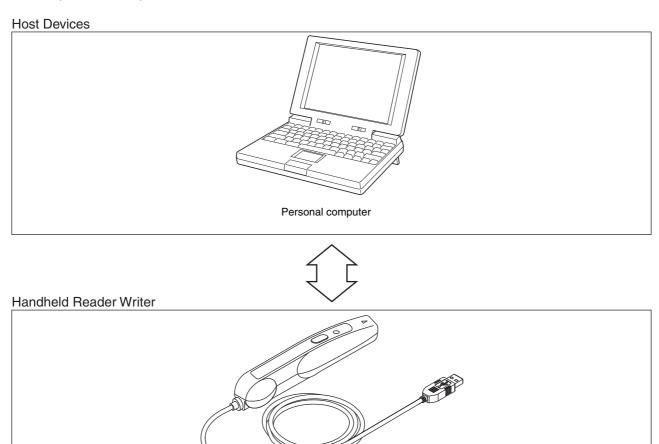
#### Antenna

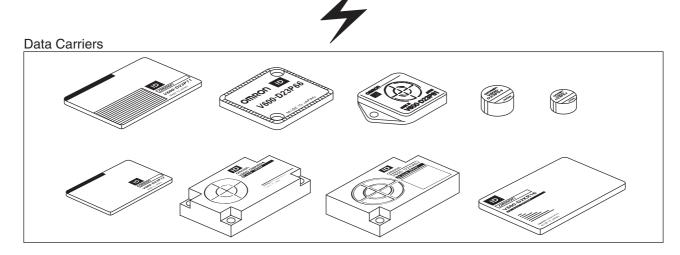
To communicate with the Data Carrier, move the antenna head closer to it.

# **System Configuration**

#### V600-CHUD

The V600-CHUD Hand-held Reader Writer can communicate with host devices that have a USB interface such as personal computers.





The V600-CHUD Hand-held Reader Writer can be used with any Data Carrier in the V600 Series.



For details on Hand-held Reader Writer and Data Carrier models, refer to Section 6 Appendices.

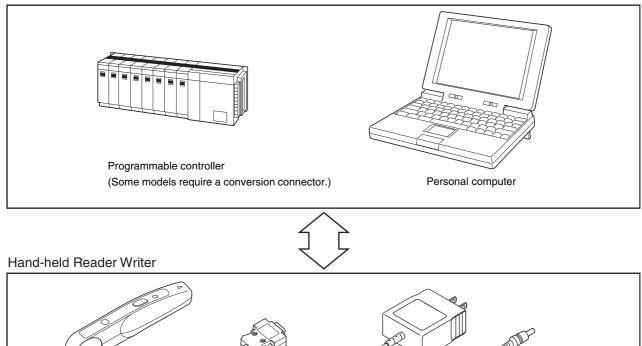


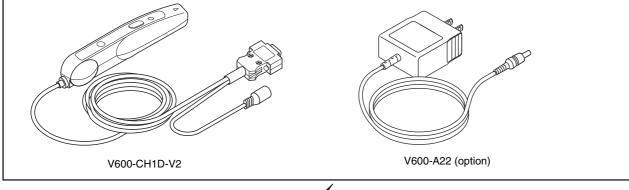
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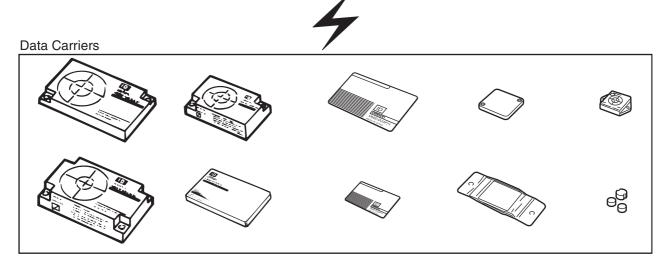
#### V600-CH1D-V2

A built-in RS-232C serial interface in the V600-CH1D-V2 Hand-held Reader Writer allows communications with personal computers and programmable controllers that are equipped with an RS-232C interface.

#### **Host Devices**







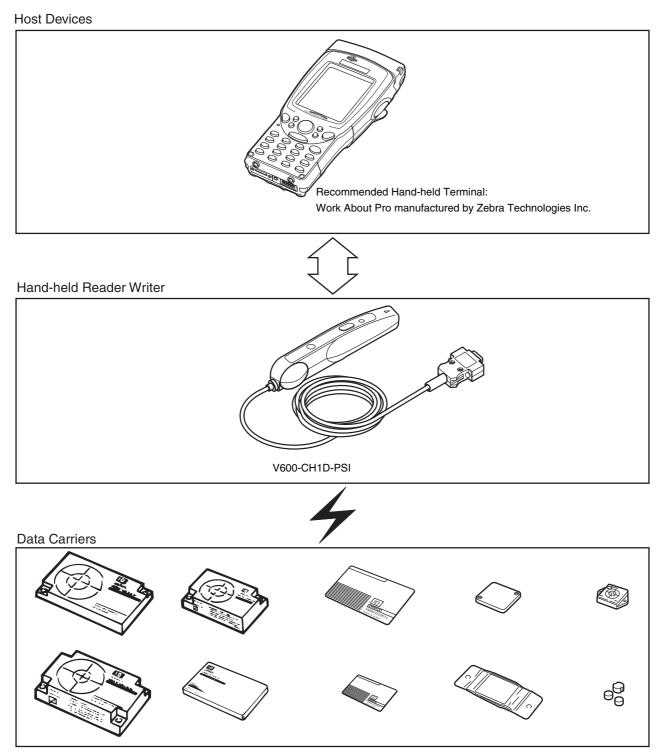
The V600-CH1D-V2 Hand-held Reader Writer can be used with any Data Carrier in the V600 Series.

For details on Hand-held Reader Writer and Data Carrier models, refer to Section 6 Appendices.

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#### V600-CH1D-PSI

A built-in RS-232C serial interface in the V600-CH1D-PSI Hand-held Reader Writer allows communications with personal computers and programmable controllers that are equipped with an RS-232C interface.



The V600-CH1D-PSI Hand-held Reader Writer can be used with any Data Carrier in the V600 Series.

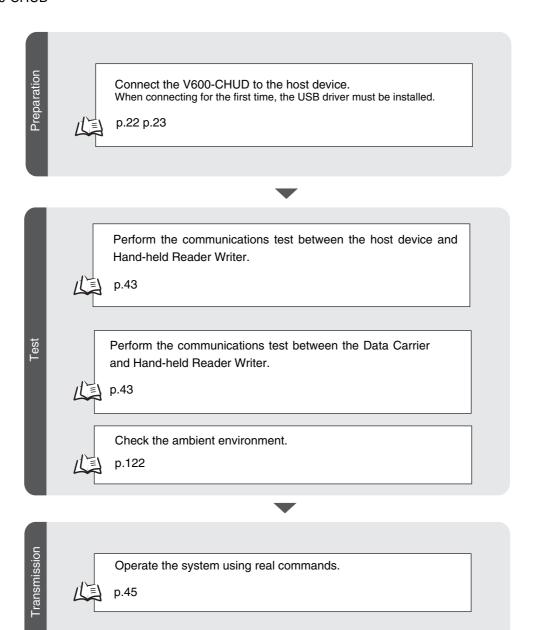


For details on Hand-held Reader Writer and Data Carrier models, refer to Section 6 Appendices.



# **Operation Flowchart**

V600-CHUD



#### V600-CH1D-V2

Connect the V600-CH1D-V2 to the host device.



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Set the communications parameters between the host device and Hand-held Reader Writer.



Perform the communications test between the host device and Hand-held Reader Writer.



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Test

Perform the communications test between the Data Carrier and Hand-held Reader Writer.





Check the ambient environment.



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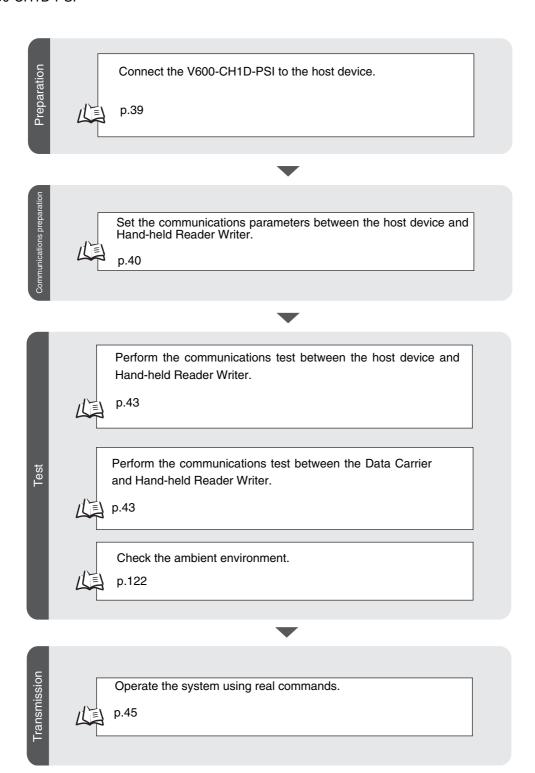
Transmission

Operate the system using real commands.



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#### V600-CH1D-PSI



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# **Section 2 Communications Preparations**

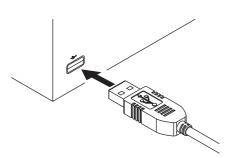
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# **V600-CHUD Communications Preparations**



### Connection

- Connecting the Cable
- 1. Connect the cable connector to the USB connector on the host device, making sure that the connector is oriented correctly and not inserted at an angle.

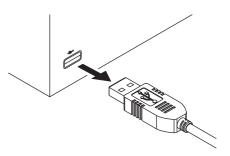


- Removing the Cable
- **1.** Remove the cable.

Close the software application at the host device and then pull out the connector in a straight line.



If the connector is removed while the software is running at the host device, operation may stop due to a software malfunction error.





### Installing the USB Driver (V600-CHUD)

When connecting the Hand-held Reader Writer to the host device for the first time, the USB driver must be installed at the host device.

#### Downloading the USB Driver

Download the USB Driver for the V680-CHUD from the web site.

For details, ask your OMRON sales representative.

#### Install the USB Driver in the Personal Computer

The V600-CHUD supports Windows 2000 and Windows XP operating systems. Install the driver in the host device following the procedure corresponding to the OS being used.

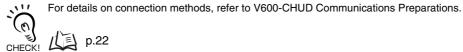
Operation on other OS is not supported.

<Windows 2000>

1. Turn ON the power to the personal computer and start Windows 2000.



**2.** Connect the Hand-held Reader Writer to the personal computer.



The following window will be displayed when the Hand-held Reader Writer is connected.

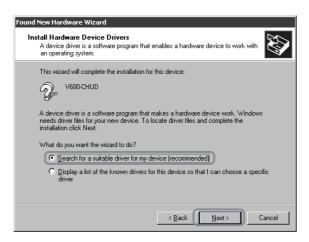




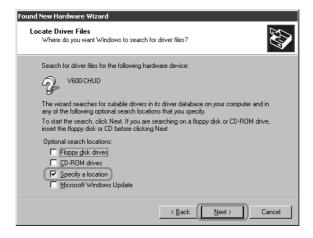
**3.** When the following window is displayed, click the **Next** Button.



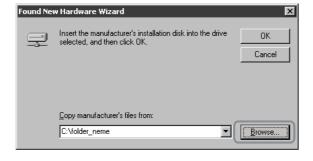
4. Select Search for a suitable driver for my device (recommended) and then click the Next Button.



**5.** Select *Specify a location* and then click the **Next** Button.



6. Click the Browse Button, and select the folder in which the downloaded file RFID-Win2kcom.inf is saved.



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## 7. Click the Next Button.



The following window will be displayed when software installation is completed.

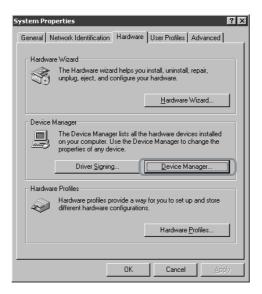


**8.** Click the **Finish** Button.

#### **Checking Installation**

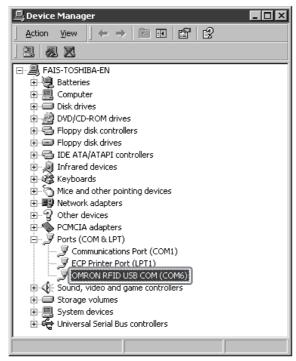
Check that the driver is correctly installed.

- **1.** Connect the Hand-held Reader Writer to the personal computer.
- 2. On the Start Menu, select Settings Control Panel System.
- **3.** Select the **Device Manager** Button on the Hardware Tab Page.



4. Select Ports (COM & LPT), and check that OMRON RFID USB COM is displayed.

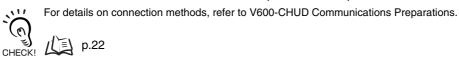
The driver is correctly installed if this port is displayed.



Communications with the Hand-held Reader Writer can be performed with the COM number displayed in parentheses after OMRON RFID USB COM.

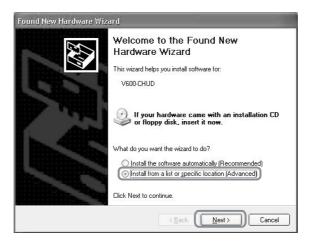
#### <Windows XP>

- **1.** Turn ON the power to the personal computer and start Windows XP.
- **2.** Connect the Hand-held Reader Writer to the personal computer.

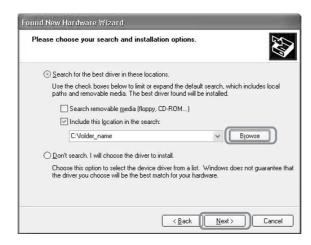


Wait for the following window to be displayed.

3. When the following window is displayed, select Install from a list or specific location (Advanced) and click the Next Button.



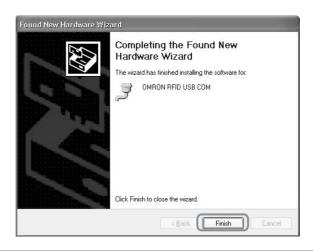
4. Click the Browse Button, and select the folder in which the downloaded file RFID-Win2kcom.inf is saved. Then click the Next Button.



**5.** Click the **Continue Anyway** Button.



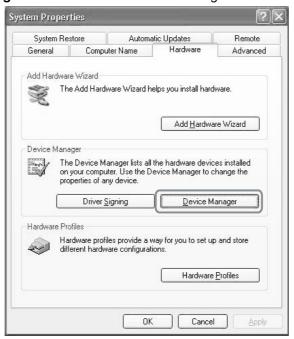
When the following window is displayed, installation is completed.



**6.** Click the **Finish** Button.

Check that the driver is correctly installed.

- **1.** Connect the Hand-held Reader Writer to the personal computer.
- 2. On the Start Menu, select Control Panel System.
- **3.** Click the **Device Manager** Button in the Hardware Tab Page.



4. Select Ports (COM & LPT), and check that OMRON RFID USB COM is displayed.

The driver is correctly installed if this port is displayed.



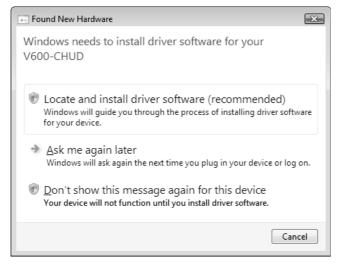
Communications with the Hand-held Reader Writer can be performed with the COM number displayed in parentheses after OMRON RFID USB COM.

- 2. Connect the Hand-held Reader Writer to the computer via USB.
  - For details on connection methods, refer to V600-CHUD Communications Preparations.

    p.22

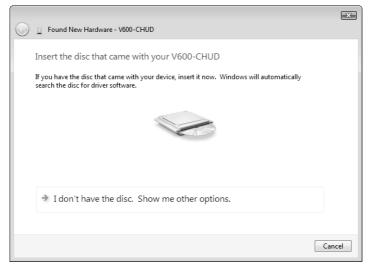
Wait for the following window to be displayed.

**3.** When the following window is displayed, select *Locate and install driver software (recommended)* Button.



- **4.** If the User Account Control Dialog Box is displayed, click the **Continue** Button.
- **5.** If a dialog box appears for searching for software online, select the **Don't search online** Option. If this dialog box is not displayed, go to the next step.

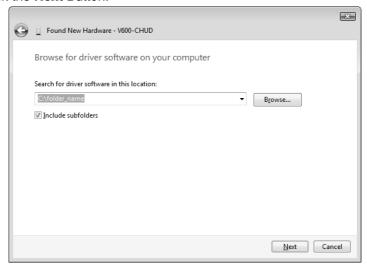
6. When the following window is displayed, select *I don't have the disc. Show me other options.* But-



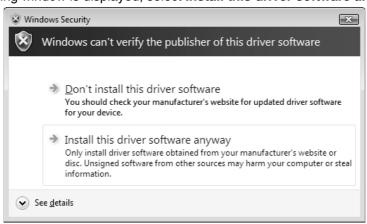
7. When the following window is displayed, select Browse my computer for driver software (advanced) Button.



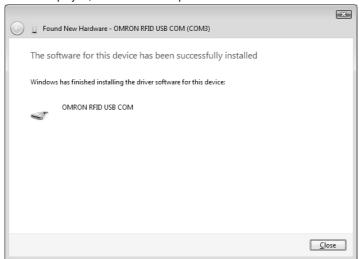
8. Click the Browse Button, and select the folder in which the downloaded file V600\_CHUD\_200.inf is saved. Then click the Next Button.



**9.** When the following window is displayed, select *Install this driver software anyway* Button.



When the following window is displayed, installation is completed.



10. Click the Close Button.



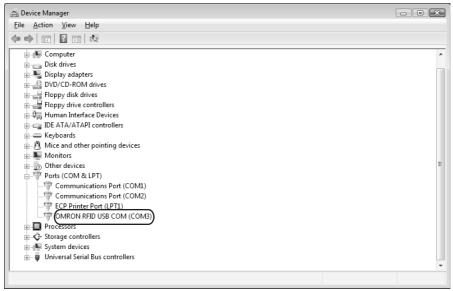
The displays that actually appear depend on your computer environment.

#### Checking Installation

Check that the driver is correctly installed.

- $oldsymbol{1}$  . Connect the Hand-held Reader Writer to the personal computer.
- 2. On the Start Menu, select *Control Panel Performance and Maintenance*.
- **3.** Click the **System** Icon.
- **4.** Click the **Device Manager** Button.
- 5. Select Ports (COM & LPT), and check that OMRON RFID USB COM is displayed.

The driver is correctly installed if this port is displayed.



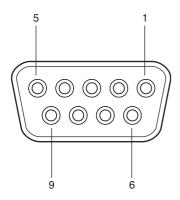
Communications with the Hand-held Reader Writer can be performed with the COM number displayed in parentheses after OMRON RFID USB COM.

# **V600-CH1D-V2 Communications Preparation**



# Pin Arrangement of the Host Device Interface Connector

V600-CH1D-V2



Pin No.	Signal	Code (See note.)	Signal direction
1			
2	Receive data	RD	Hand-held Reader Writer to host device
3	Send data	SD	Host device to Hand-held Reader Writer
4			
5	Signal ground	SG	
6	Data set ready	DS	Hand-held Reader Writer to host device
7	Request send	RS	Loops inside connector
8	Enable send	CS	
9			

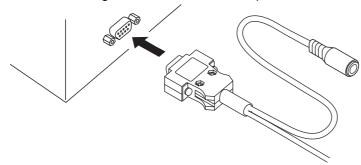
Note: The names of signals at the host device are abbreviated with codes.

Note: For conversion to a 25-pin connector, the SGC-X9P/25P-2 manufactured by Sunhayato, or an equivalent, is recommended.

#### Connection with the Host Device

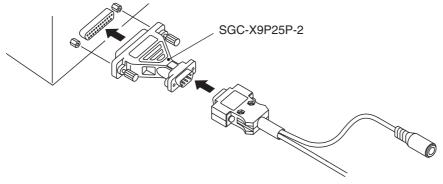
Use the following procedure to connect the V600-CH1D-V2 to the host device.

- 1. Connect the V600-CH1D-V2 to the RS-232C interface of the host device.
  - •When connecting to an IBM PC/AT or compatible:

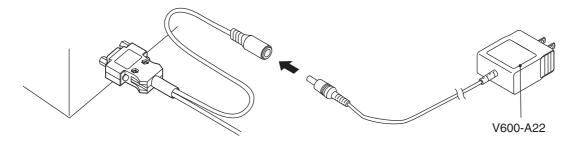


•When connecting to a PC9801 series computer (D-Sub 25-pin connector):

To convert from a 9-pin connector to a 25-pin connector, use an SGC-X9P25P-2 conversion connector manufactured by Sunhayato, or an equivalent product.



**2.** Connect the V600-A22 AC Adaptor to the V600-CH1D-V2.



- **3.** Plug the V600-A22 AC Adaptor into a 100- to 120-VAC power outlet.
  - Do not use any AC adaptor other than the specified one (V600-A22). • Using any AC adaptor other than the specified one may cause a malfunction, damage, or fire in the V600-CH1D-V2.
    - Some host devices require a conversion connector.

#### When connecting to a CQM1, CJ1, CS1, etc.

Prepare a connection cable as shown in the connection examples below.

Note: Because both the V600-CH1D-V2 interface connector and the interface connector of the CQM1, CJ1, and CS1 are sockets, a conversion connector is necessary to connect them. Also, the pin arrangement of the CQM1, CJ1, and CS1 interface connector is different from the RS-232C pin arrangement of a personal computer.

#### V600-CH1D-V2

Pin No.	Signal
1	
2	RD
3	SD
4	
5	SG
6	DS
7	RS
8	CS
9	

#### CQM1/CJ1/CS1

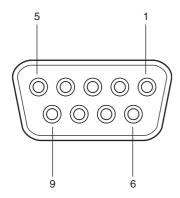
Pin No.	Signal
1	
2	SD
3	RD
4	RS
5	CS
6	
7	
8	
9	SG

# **V600-CH1D-PSI Communications Preparation**



# Pin Arrangement of the Host Device Interface Connector

V600-CH1D-PSI



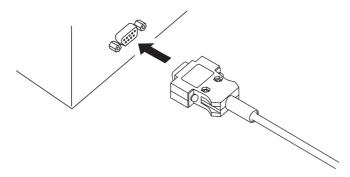
Pin No.	Signal	Code (See note.)	Signal direction
1			
2	Receive data	RD	Hand-held Reader Writer to host device
3	Send data	SD	Host device to Hand-held Reader Writer
4			
5	Signal ground	SG	
6	Data set ready	DS	Hand-held Reader Writer to host device
7	Request send	RS	Loops inside connector
8	Enable send	CS	
9	5 VDC		Host device to Hand-held Reader/Writer

Note: The names of signals at the host device are abbreviated with codes.

#### Connection with the Host Device

Use the following procedure to connect the V600-CH1D-PSI to the host device.

**1.** Connect the V600-CH1D-PSI to the RS-232C interface of the host device.



# V600-CH1D-PSI Communications Preparation Section 2



# Setting the Hand-held Reader Writer

#### Settings

The following settings are used to operate the Hand-held Reader Writer.

- •Serial communications parameters (data transfer speed, parity check, stop bits).
- Basic function settings (Auto Command OFF and Normal Operation Output functions)

These settings can be changed by using a setting command from the host device. To operate the Hand-held Reader Writer with the new setting, the power must be turned OFF then ON again, or the ABORT command must be used.

#### Serial Communications Parameters

The following are the settings related to serial communications. Use the COMMUNICATIONS CONDI-TIONS SETTING (TR) command.

Item	Contents
Baud rate (bps)	2400, 4,800, 9,600 (see note), 19,200, 38,400
Transmission code	7-unit ASCII 7* (see note) or 8-unit JIS 8
Parity check	Even parity* (see note)/odd parity/none
Stop bits	2* (see note)/1

Note: Items marked by an asterisk (\*) are set as the default when shipped from the factory.

#### **Basic Function Settings**

The Auto Command OFF and Normal Operation Output functions can be set. Use the BASIC FUNC-TIONS SETTING (FN) command

Item	Contents
Auto Command OFF function	Yes (1 minute)*, No
Normal Operation Output function	No*, Yes

Note: Items marked by an asterisk (\*) are set as the default when shipped from the factory.

#### Reading the Settings

Use the SET INFORMATION READ (UL) command to read the settings of the Hand-held Reader Writer. The information read by the SET INFORMATION READ command is set in the backup memory of the Hand-held Reader Writer. For this reason, care must be taken when the power is first turned ON after the settings have been changed because the operational settings of the Hand-held Reader Writer will be different.

#### Initializing the Settings

A setting command is used to set the Hand-held Reader Writer but if the communications parameters are not known or if the setting contents are damaged, it is possible that communications will no longer be possible with the host device. If this occurs, press both the reset button and the activate switch when turning ON the power. This will return all settings to the defaults set when the Hand-held Reader Writer was shipped from the factory, allowing communications with the host device again.

#### •Reset Procedure

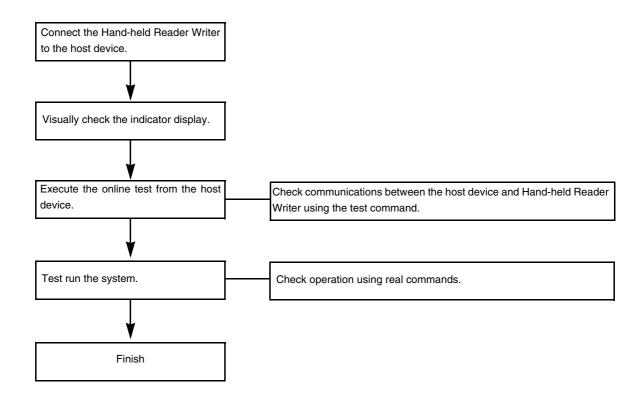
- **1.** Turn ON the power while pressing the reset button.
- 2. Keep the reset button depressed for two seconds or more. The green operation indicator will start flashing.
- **3.** With the green operation indicator flashing, remove your finger from the reset button and press the activate switch.
- **4.** When the activate switch is pressed, the operation indicator will stop flashing green. This indicates that all of the settings have been initialized.

Note: If the activate switch is not pressed within 30 seconds from the time that the operation indicator starts flashing green, the settings will not be initialized.

# **Communications Test**



#### **Test Run Procedure**



# Communications Test Between Host Device and Hand-held **Reader Writer**

Use the test command to test communications between the Hand-held Reader Writer and host device. Before performing communications with the Data Carrier, check the Hand-held Reader Writer connections and communications.

**1.** Send the test command from the host device.



For detail on the test command, refer to TEST (TS).





2. If communications is normal, the Hand-held Reader Writer will return the received data.



If a response is not returned, refer to Troubleshooting.



# Communications Test Between the Data Carrier and Hand-held **Reader Writer**

Use a real command to test communications between the Data Carrier and the Hand-held Reader Writer.

1. Send the auto read command (AR) from the host device.



For details on the auto read command, refer to AUTO READ (AR).

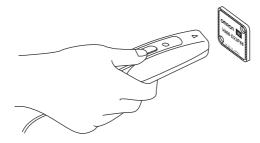






The Hand-held Reader Writer will communicate with the Data Carrier and the operation indicator will flash green.

**2.** Move the antenna section of the Hand-held Reader Writer close to the Data Carrier.





The Hand-held Reader Writer will read the data in the Data Carrier when the Hand-held Reader Writer moves within the communications range. As a result, the operation indicator will be light green and then turn OFF.

MEMO

# **Section 3 Commands**

Communications with the Data Carrier	46
Command and Response Format	50
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Communications Subcommands	94
Most Commands	95
Controller Control Commands	96
Other Commands	100
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# Communications with the Data Carrier

There are 4 types of commands for communicating with the Data Carrier using the Hand-held Reader Writer.

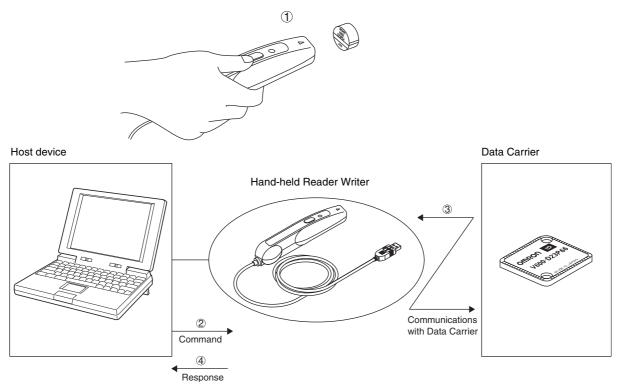
- Normal commands
- Button commands
- Auto commands
- •Button auto commands



#### **Normal Commands**

Normal commands are sent from the host device for communications with the Data Carrier, after the antenna end of the Hand-held Reader Writer has been moved close to the Data Carrier.

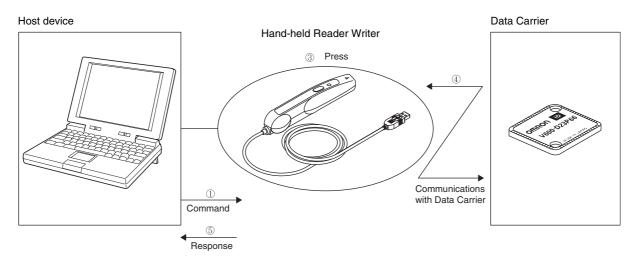
1. Move the antenna end of the Hand-held Reader Writer close to the Data Carrier.



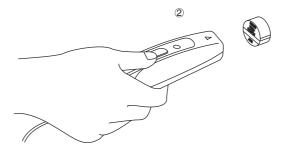
- 2. Commands are sent from the host device to the Hand-held Reader Writer.
- 3. The Hand-held Reader Writer communicates with the Data Carrier.
- 4. A response is returned from the Hand-held Reader Writer to the host device. If communications are normal, the operation indicator (LED) lights green and then turns OFF. If the Data Carrier is not detected within the Hand-held Reader Writer's communication area when the command is sent from the host device, a Data Carrier Non-existent Error will occur. At this time, the operation indicator will flash red.

#### **Button Commands**

Button commands used to perform communications with the Data Carrier are activated when the activate switch is pressed after commands are sent from the host device, and the antenna end of the Hand-held Reader Writer has been moved close to the Data Carrier.



- 1. A command is sent from the host device to the Hand-held Reader Writer. As a result, the operation indicator will light green.
- 2. Move the antenna end of the Hand-held Reader Writer close to the Data Carrier.

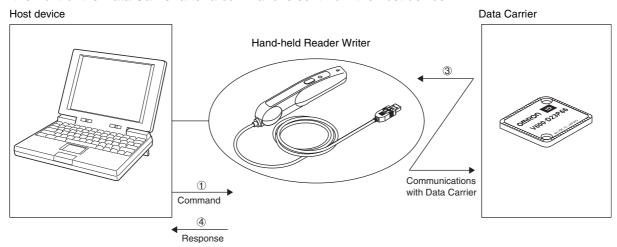


- 3. Press the Hand-held Reader Writer activate switch.
- 4. The Hand-held Reader Writer communicates with the Data Carrier.
- 5. A response is returned to the host device from the Hand-held Reader Writer. If communications are normal, the operation indicator (LED) lights green and then turns OFF. If the Data Carrier is not detected within the Hand-held Reader Writer's communication area when the activate switch is pressed, a Data Carrier Non-existent Error will occur. At this time, the operation indicator will flash red.

# Communications with the Data Carrier Section 8

#### **Auto Commands**

Auto commands can execute communications with the Data Carrier when the antenna is moved near the front of the Data Carrier after a command is sent from the host device.

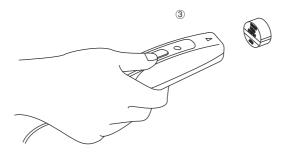


- 1. A command is sent from the host device to the Hand-held Reader Writer.
- 2. The Hand-held Reader Writer enters the communication stand-by state with the Data Carrier, and the operation indicator (LED) flashes green.



If the Data Carrier is not detected within one minute of sending the command, a timeout will occur and a Data Carrier Non-existent Error will occur. As a result, the operation indicator will flash red.

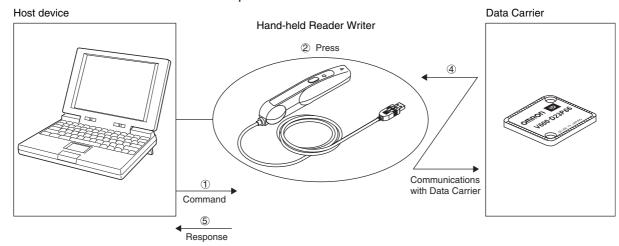
3. Communications with the Data Carrier are performed when the antenna end of the Hand-held Reader Writer is moved near the Data Carrier.



4. A response is returned from the Hand-held Reader Writer to the host device. If communications end normally, the operation indicator (LED) lights green and then turns OFF.

#### **Button Auto Commands**

Button auto commands execute auto commands after a command is sent from the host device and the activate switch of the Hand-held Reader Writer is pressed.

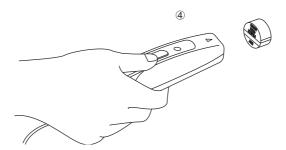


- 1. A command is sent from the host device to the Hand-held Reader Writer.
- 2. Press the Hand-held Reader Writer activate switch.
- 3. The Hand-held Reader Writer enters the communication stand-by state with the Data Carrier, and the operation indicator (LED) flashes green.



If the Data Carrier is not detected within one minute of sending the command, a timeout will occur and a Data Carrier Non-existent Error will occur. As a result, the operation indicator will flash red.

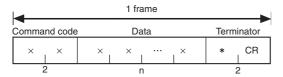
4. Communications with the Data Carrier are performed when the antenna end of the Hand-held Reader Writer is moved near the Data Carrier.



5. A response is returned from the Hand-held Reader Writer to the host device. If communications end normally, the operation indicator (LED) lights green and then turns OFF.

# **Command and Response Format**

The format of commands sent between the host computer and the Hand-held Reader Writer and responses returned from the Hand-held Reader Writer to the host computer is shown below. The command and response both consist of a single frame. The frame (including the terminator) consists of up to 4,106 characters for commands and 4,102 characters for responses.



Name	Description
Command code	Command: Contains the two-character code (see page p.52). Response: Contains the same code that was sent with the command.
Data	Contains the details of the command and response, as follows:  •ASCII/hexadecimal code specification, processing specification, mode specification  •Processing area number specification  •Processing start address  •Number of bytes to be read, write data
Terminator	Indicates end of command/response.

# **Specifying Data Code**

Whether the read or write data is treated as an ASCII (or JIS 8) code or hexadecimal code is specified in a command.

#### ASCII (JIS 8 Code)

•One character of ASCII or JIS 8 code data occupies 1 byte (1 address) of the Data Carrier memory.

#### •Example of Specifying ASCII Code

W	Т	Α	1	0	0	1	0	0	М	R	0	N	*	CR
Command code ASCII Processing Start address							v	Vrite dat	а		Term	inator		
		setting	area nun	nber					-		-			

#### Data Carrier

Address			ĺ
0010	4	F	"O'
0011	4	D	"M'
0012	5	2	"R"
0013	4	F	"O'
0014	4	E	"N'

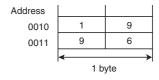
#### •Hexadecimal Code

- •One character is treated as a hexadecimal number. Therefore, only numerals 0 through 9 and A to F can be accepted.
- •Two characters of data occupy 1 byte (1 address) of the Data Carrier memory. Therefore, specify data in 2-character units (in even numbers) when using a WRITE command. If an odd number of characters is specified by mistake, an error will occur.

#### •Example of Specifying Hexadecimal Code



#### Data Carrier





## **Command List**

Commands can be classified into four major types.

#### •Communications Commands

The following commands are used for communications with the Data Carrier.

Command code	Command name	Function	Page
RD	READ	Reads memory data from the Data Carrier.	p.54
WT	WRITE	Writes data to the memory of the Data Carrier.	p.56
AR	AUTO READ	Reads data from the Data Carrier when the Data Carrier is within the communications area.	p.58
AW	AUTO WRITE	Writes data to the memory of the Data Carrier when the Data Carrier is within the communications area.	p.60
BR	BUTTON READ	Reads data from the memory of the Data Carrier when the activate switch is pressed.	p.62
BW	BUTTON WRITE	Writes data to the memory of the Data Carrier when the activate switch is pressed.	p.64
UR	BUTTON AUTO READ	Reads data from the Data Carrier when the Data Carrier enters the communications area after the activate switch is pressed.	p.66
UW	BUTTON AUTO WRITE	Writes data to the memory of the Data Carrier when the Data Carrier enters the communications area after the activate switch is pressed.	p.68
RC	COPY READ	Reads data to be copied using the COPY WRITE command from the Data Carrier.	p.70
WC	COPY WRITE	Writes the data read using the COPY READ command to the Data Carrier.	p.71
XR	EXPANSION DIVIDED READ	Divides and reads up to 2 Kbytes of data from the Data Carrier.	p.72
XW	EXPANSION DIVIDED WRITE	Divides and writes up to 2 Kbytes of data to the Data Carrier.	p.74
NR	EXPANSION DIVIDED AUTO READ	Divides and reads up to 2 Kbytes of data from the Data Carrier when the Data Carrier enters the communications area.	p.76
NW	EXPANSION DIVIDED AUTO WRITE	Divides and writes up to 2 Kbytes of data to the Data Carrier when the Data Carrier enters the communications area.	p.78
rd	EXPANSION BATCH READ	Reads up to 2 Kbytes of data from the Data Carrier in a batch.	p.80
wt	EXPANSION BATCH WRITE	Writes up to 2 Kbytes of data to the Data Carrier in a batch.	p.81
ar	EXPANSION BATCH AUTO READ	Reads up to 2 Kbytes of data from the Data Carrier in a batch when the Data Carrier enters the communications area.	p.82
aw	EXPANSION BATCH AUTO WRITE	Writes up to 2 Kbytes of data to the Data Carrier in a batch when the Data Carrier enters the communications area.	p.83
br	EXPANSION BATCH BUTTON READ	Reads up to 2 Kbytes of data from the Data Carrier in a batch after the activate switch is pressed.	p.84
bw	EXPANSION BATCH BUTTON WRITE	Writes up to 2 Kbytes of data to the Data Carrier in a batch after the activate switch is pressed.	p.85
ur	EXPANSION BATCH BUTTON AUTO READ	Reads up to 2 Kbytes of data from the Data Carrier in a batch when the Data Carrier enters the communications area after the activate switch is pressed.	p.86

Command code	Command name	Function	Page
uw	EXPANSION BATCH BUTTON AUTO WRITE	Writes up to 2 Kbytes of data to the Data Carrier in a batch when the Data Carrier enters the communications area after the activate switch is pressed.	p.87
CW	CALCULATION WRITE	Writes the calculation results for the memory data to the Data Carrier.	p.88
FL	FILL	Writes data for the specified number of write bytes beginning from the write start address specified in the command.	p.89
fl	EXPANSION BATCH FILL	Writes data for the specified number of write bytes beginning from the write start address specified in the command. Up to 2 Kbytes of data can be written in a batch.	p.91
MDC/K	DATA CHECK	Calculates or compares memory check codes in the Data Carrier.	p.92
MDS	OVERWRITE COUNT CONTROL	Controls the number of overwrites for EEPROM Data Carriers.	p.93

#### •Communications Subcommands

These commands are used to cancel command execution.

Command code	Command name	Function	Page
AA	COMMAND PRO- CESSING TERMI- NATE	Forcedly ends communications with the Data Carrier.	p.94

#### Host Commands

These commands are used to test communications between the Hand-held Reader Writer and host device.

Command code	Command name	Command name Function					
TS	TEST	Confirms the communications status between the Hand-held Reader Writer and host device. The data sent from the host device is returned as is.	p.95				
VS	VERSION READ	Reads the Hand-held Reader Writer's model information, software version and software creation date.	p.95				

#### Controller Control Commands

These commands are used to reset the Controller or set serial communications.

Command code	Command name	Function	Page
XZ	ABORT	Resets the Controller.	p.96
TR	COMMUNICA- TIONS CONDI- TIONS SETTING	Sets communications parameters for communications with the host device.	p.97
FN	BASIC FUNC- TIONS SETTING	Sets the Specify Auto Command OFF function and Specify Normal Operation Output function.	p.98
UL	SET INFORMA- TION READ	Reads the settings data for the Hand-held Reader Writer.	p.99

# **Communications Commands**

Details of communications commands used to communicate with the Data Carrier are provided here.

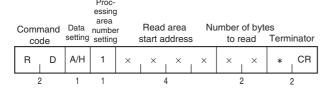


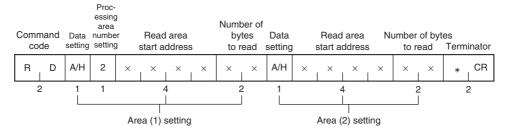
## READ (RD)

This command reads data from the Data Carrier. If the Data Carrier is not in the communications area, an error response (end code: 72 = Data Carrier non-existent) will be returned.

Command

#### Processing area number: 1



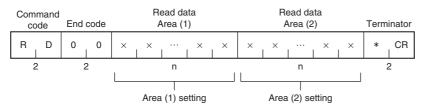


Data sattina	Cota the code female would be coded upon more female date
Data setting	Sets the code format used to send responses for read data.
	A: ASCII
	H: Hexadecimal code
	When multiple processing areas are used, ASCII and hexadecimal code can be specified at the
	same time within a single command frame.
Processing area number	Specifies the processing area number.
setting	Setting range: 1 to 9, A (A = 10)
Read area start address	Specifies the start address of the area to be read from the Data Carrier in 4-digit hexadecimal code.
	Setting range: 0000h to 1FFFh
	When multiple processing areas are used, specify the areas in order starting from the smallest
	address. The same area cannot be specified twice.
Number of butes to read	·
Number of bytes to read	Specifies the number of bytes to be read from the Data Carrier in 2-digit hexadecimal code. The
	maximum number of bytes that can be read at one time is 256 bytes, as follows:  •ASCII: 256 bytes (256 characters)
	, ,
	Hexadecimal code: 256 bytes (512 characters)
	Cotting range; OOb to FFb (OO OFC butco)
	Setting range: 00h to FFh (00 = 256 bytes)
	When multiple processing areas are used, set so that the total number of bytes from all areas to be
	read is within 256 bytes, as follows:
	Area (1) bytes ++ Area (N) bytes ≤ 256 bytes

Response

#### Processing Area Number: 1





End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> .  p.101
Read data	Specifies the data read from the Data Carrier.  The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.



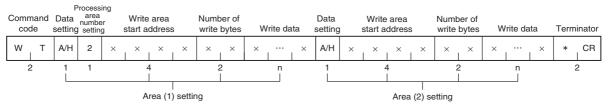
# WRITE (WT)

This command writes data to the Data Carrier. If the Data Carrier is not in the communications area, an error response (end code: 72 = Data Carrier non-existent) will be returned.

Command

#### Processing Area Number: 1





Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code  When multiple processing areas are used, ASCII and hexadecimal code can be specified at the same time within a single command frame.
Processing area number setting	Specifies the processing area number. Setting range: 1 to 9, A (A = 10)
Write area start address	Specifies the start address of the area in the Data Carrier to be written to in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh  When multiple processing areas are used, specify the areas in order starting from the smallest address. The same area cannot be specified twice.
Number of write bytes	When multiple processing areas are used, specifies the number of bytes to be written to the Data Carrier in 2-digit hexadecimal code. The maximum number of bytes that can be written at one time is 256 bytes, as follows:  • ASCII: 256 bytes (256 characters)  • Hexadecimal code: 256 bytes (512 characters)  Setting range: 01h to FFh  When multiple processing areas are used, set so that the total number of bytes to be written for all areas is within 256 bytes, as follows:  Area (1) bytes ++ Area (N) bytes ≤ 256 bytes
Write data	Specifies the write data from the Data Carrier.  The characters in ASCII indicate the number of write bytes and the characters in hexadecimal code indicate the number of write bytes x 2.

Response Command code Terminator W Т 0 0 CR 2 2 2 End code Indicates the execution result for the command. The end code 00 indicates normal completion. For details on end codes, refer to End code List. p.101



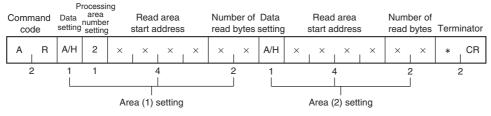
# **AUTO READ (AR)**

This command reads data from the Data Carrier when the Data Carrier enters the communications area. The Hand-held Reader Writer responds when the communication between the Hand-held Reader Writer and Data Carrier has ended.

Command

#### Processing Area Number: 1



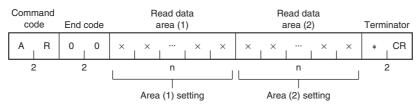


Data setting	Specifies the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code  When multiple processing areas are used, ASCII and hexadecimal code can be specified at the
	same time within a single command frame.
Processing area number setting	Specifies the processing area number. Setting range: 1 to 9, A (A = 10)
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh  When multiple processing areas are used, specify the areas in order starting from the smallest
	address. The same area cannot be specified twice.
Number of read bytes	When multiple processing areas are used, specifies the number of bytes to be read from the Data Carrier in 2-digit hexadecimal code.  The maximum number of bytes that can be read at one time is 256 bytes.  •ASCII: 256 bytes (256 characters)  •Hexadecimal code: 256 bytes (512 characters)  Setting range: 00h to FFh (00 = 256 bytes)
	When multiple processing areas are used, set so that the total number of bytes to be read for all areas is within 256 bytes, as follows:  Area (1) bytes ++ Area (N) bytes ≤ 256 bytes

Response

#### Processing Area Number: 1

	mand de	End	code		R	ead da	ata		Term	inator
А	R	0	0	×	×		×	×	*	CR
2		2	2			n			2	2



End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> .  p.101
Read data	Specifies the data read from the Data Carrier.  The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.

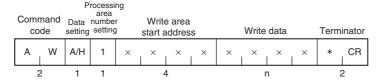


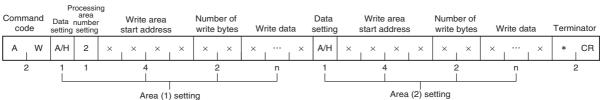
# **AUTO WRITE (AW)**

This command writes data to the Data Carrier when the Data Carrier enters the communications area. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended.

Command

#### Processing Area Number: 1





	Area (1) setting	Area (2) setting
Data setting	A: ASCII H: Hexadecimal code	to send responses for read data.  areas are used, ASCII and hexadecimal code can be specified at the command frame.
Processing area number setting	Specifies the processing a Setting range: 1 to 9, A (A	rea number.
Write area start address	code. Setting range: 0000h to 1F	areas are used, specify the areas in order starting from the smallest
Number of write bytes	Carrier in 2-digit hexadecii The maximum number of I •ASCII: 256 bytes (256 che •Hexadecimal code: 256 b Setting range: 01h to FFh When multiple processing areas is within 256 bytes,6	bytes that can be written at one time is 256 bytes.  aracters)  ytes (512 characters)  areas are used, set so that the total number of bytes to be written for all
Write data	Indicates the data to be wi	itten to the Data Carrier. dicate the number of write bytes and the characters in hexadecimal code

Response Command code 0 CR 2 2 2 End code Indicates the execution result for the command. The end code 00 indicates normal completion. For details on end codes, refer to End code List. p.101



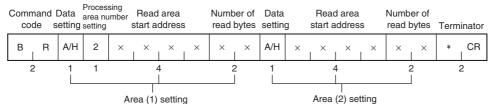
# **BUTTON READ (BR)**

After this command is received by the Hand-held Reader Writer, data is read from the Data Carrier by pressing the activate switch. If the activate switch is pressed and the Data Carrier is not in communications range, an error response (end code: 72 = Data Carrier non-existent) will be returned.

Command

#### Processing Area Number: 1



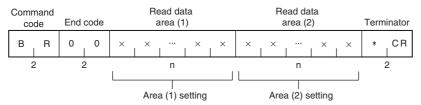


Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code  When multiple processing areas are used, ASCII and hexadecimal code can be specified at the same time within a single command frame.
Processing area number setting	Specifies the processing area number. Setting range: 1 to 9, A (A = 10)
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh  When multiple processing areas are used, specify the areas in order starting from the smallest address. The same area cannot be specified twice.
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 2-digit hexadecimal.  The maximum number of bytes that can be read at one time is 256 bytes.  •ASCII: 256 bytes (256 characters)  •Hexadecimal code: 256 bytes (512 characters)  Setting range: 00h to FFh (00 = 256 bytes)  When multiple processing areas are used, set so that the total number of bytes to be read for all areas is within 256 bytes, as follows:  Area (1) bytes ++ Area (N) bytes ≤ 256 bytes

Response

#### Processing Area Number: 1

Com	mand										
C	code End code				End code Read data				Terminator		
В	R	0	0	×	×		×	×	*	CR	
2		2	2			n				2	



End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> .  p.101
Read data	Indicates the data read from the Data Carrier.  The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.



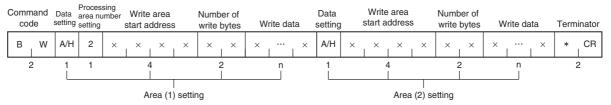
# **BUTTON WRITE (BW)**

After this command is received by the Hand-held Reader Writer, data is written to the Data Carrier by pressing the activate switch. If the activate switch is pressed and the Data Carrier is not in communications range, an error response (end code: 72 = Data Carrier non-existent) will be returned.

Command

#### Processing Area Number: 1





Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code  When multiple processing areas are used, ASCII and hexadecimal code can be specified at the same time within a single command frame.
Processing area number setting	Specifies the processing area number. Setting range: 1 to 9, A (A = 10)
Write area start address	Specifies the start address of the area in the Data Carrier to be written to in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh  When multiple processing areas are used, specify the areas in order starting from the smallest address. The same area cannot be specified twice.
Number of write bytes	When multiple processing areas are used, specifies the number of bytes to be written to the Data Carrier in 2-digit hexadecimal.  The maximum number of bytes that can be written at one time is 256 bytes.  •ASCII: 256 bytes (256 characters)  •Hexadecimal code: 256 bytes (512 characters)  Setting range: 01h to FFh  When multiple processing areas are used, set so that the total number of bytes to be written for all areas is within 256 bytes, as follows:
Write data	Area (1) bytes ++ Area (N) bytes ≤ 256 bytes  Indicates the data to be written to the Data Carrier.  The characters in ASCII indicate the number of write bytes and the characters in hexadecimal code indicate the number of write bytes x 2.

Response Command End code Terminator code 0

End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> .  p.101

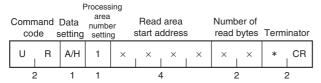


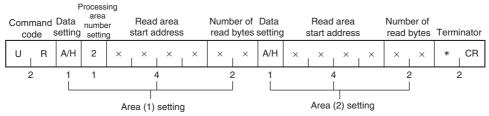
# **BUTTON AUTO READ (UR)**

After this command is received by the Hand-held Reader Writer, data will be read from the Data Carrier after the activate switch is pressed and the Hand-held Reader Writer is close to the Data Carrier. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended.

Command

#### Processing Area Number: 1



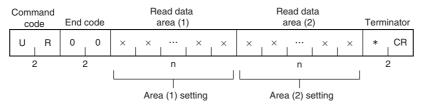


Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code  When multiple processing areas are used, ASCII and hexadecimal code can be specified at the
	same time within a single command frame.
Processing area number setting	Specifies the processing area number. Setting range: 1 to 9, A (A = 10)
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
	When multiple processing areas are used, specify the areas in order starting from the smallest address. The same area cannot be specified twice.
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 2-digit hexadecimal.  The maximum number of bytes that can be read at one time is 256 bytes.  •ASCII: 256 bytes (256 characters)  •Hexadecimal code: 256 bytes (512 characters)  Setting range: 00h to FFh (00 = 256 bytes)
	When multiple processing areas are used, set so that the total number of bytes to be read for all areas is within 256 bytes, as follows:  Area (1) bytes ++ Area (N) bytes ≤ 256 bytes

Response

#### Processing Area Number: 1

Com	mand									
CC	ode	End (	code		Re	ead da	ta		Term	inator
U	R	0	0	×	×		×	×	*	CR 
	2	2	)			n			- :	2



End code	Indicates the execution result for the command.					
	The end code 00 indicates normal completion.					
	For details on end codes, refer to <i>End code List</i> .  p.101					
Read data	Indicates the data read from the Data Carrier.  The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.					



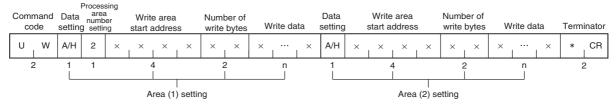
# **BUTTON AUTO WRITE (UW)**

After this command is received by the Hand-held Reader Writer, data will be written to the Data Carrier after the activate switch is pressed and the Hand-held Reader Writer is close to the Data Carrier. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended.

Command

#### Processing Area Number: 1





Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code  When multiple processing areas are used, ASCII and hexadecimal code can be specified at the same time within a single command frame.
Processing area number setting	Specifies the processing area number. Setting range: 1 to 9, A (A = 10)
Write area start address	Specifies the start address of the area in the Data Carrier to be written to in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh  When multiple processing areas are used, specify the areas in order starting from the smallest address. The same area cannot be specified twice.
Number of write bytes	When multiple processing areas are used, specifies the number of bytes to be written to the Data Carrier in 2-digit hexadecimal.  The maximum number of bytes that can be written at one time is 256 bytes.  •ASCII: 256 bytes (256 characters)  •Hexadecimal code: 256 bytes (512 characters)  Setting range: 01h to FFh  When multiple processing areas are used, set so that the total number of bytes to be written for all areas in within 256 bytes, as follows:
	areas is within 256 bytes, as follows:  Area (1) bytes ++ Area (N) bytes ≤ 256 bytes
Write data	Indicates the data to be written to the Data Carrier.  The characters in ASCII indicate the number of write bytes and the characters in hexadecimal code indicate the number of write bytes x 2.

Response Command End code code U CR 2 2 2 End code Indicates the execution result for the command. The end code 00 indicates normal completion. For details on end codes, refer to End code List. p.101



# **COPY READ (RC)**

This command reads data to be copied using the COPY WRITE (WC) command. A response is not sent for read data.

Command



Data setting	Always H.
Processing area number setting	Always 1.
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code (can be omitted).  Setting range: 0000h to 1FFFh (when omitted, all areas in the Data Carrier are read)  Note: If omitting the start address, also omit the number of read bytes. All areas of an 8-Kbytes Data Carrier cannot be copied.
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 4-digit hexadecimal.  Setting range: 0001h to 0800h

Response

code		End	code	Terminator			
F	R C		0	0	*	CR	
2		2	2	2			

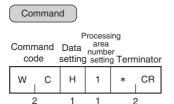
End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to End code List.  p.101



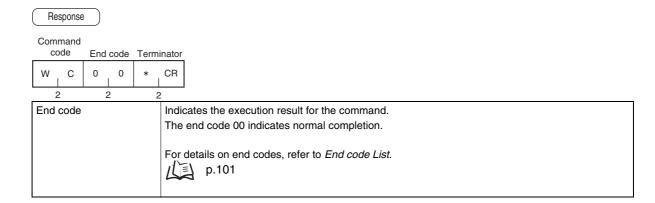
The COPY READ command can be executed more than once for data that has already been copied. If the copy operation fails, however, the copied data that was held will be deleted.  $\label{eq:copy}$ 

### **COPY WRITE (WC)**

This command writes data to the Data Carrier that was read using the COPY READ (RC) command. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended.



Data setting	Always H.
Processing area number	Always 1.
setting	





### **EXPANSION DIVIDED READ (XR)**

This command divides and reads up to 2 Kbytes of data. If the Data Carrier is not in communications range, an error response (end code: 72 = Data Carrier non-existent) will be returned. The host device cannot send commands to the Hand-held Reader Writer until all the responses have been received.

Command

Processing area  Command Data number code setting setting			r	Read area start address			Number of read bytes				Terminator		
х	R	A/H	1	×	×	×	×	×	×	×	×	*	CR
	2	1	1			1			4	1			2

Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 4-digit hexadecimal.  The maximum number of bytes that can be read at one time is 2,048 bytes.  Setting range: 0001h to 0800h  •ASCII: 2,048 bytes (2,048 characters)  •Hexadecimal code: 2,048 bytes (4,096 characters)

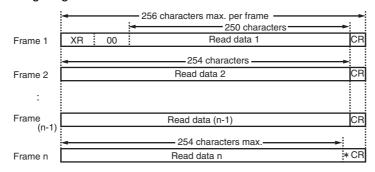
When the read data is within 250 characters.

Comi	mand de	End	code		R	Term	inator			
Х	R	0	0	×	×		×	×	*	CR
	2	2	2			n			- 2	2

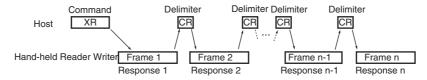
End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> .  p.101
Read data	Indicates the data read from the Data Carrier.  The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.

When the read data is 251 characters or higher.

The data received from the host device is divided into frames according to the delimiters (CR), as shown in the following diagram.



#### Communications Procedure





### **EXPANSION DIVIDED WRITE (XW)**

Divides and writes up to 2 Kbytes of data. If the Data Carrier is not in communications range, an error response (end code: 72 = Data Carrier non-existent) will be returned.

The host device cannot send commands to the Hand-held Reader Writer until all the responses have been received.

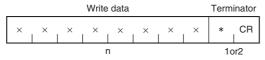
Command

#### Frame 1

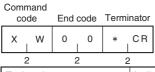
Comman code		rocess area numbe g settin	er	Writ start	e area addre			Write	data		Term	inator
x w	A/H	1	×	×	×	×	×	×	×	×	*	CR
2	1	1		-	4			r	1		10	r2

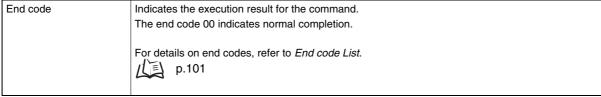
Data setting	Specifies the code format used to send write data to the Data Carrier.
	A: ASCII
	H: Hexadecimal code
Processing area number setting	Always 1.
Write area start address	Specifies the start address of the area to be written to in 4-digit hexadecimal.  Setting range: 0000h to 1FFFh
Write data	Indicates the data to be written to the Data Carrier.  Data can be between 0 and 257 characters.
Terminator	Indicates the end of the frame. CR: Succeeding frame *CR: No succeeding frame

#### Frames 2 to N



Write data	Indicates the data to be written to the Data Carrier. Data can be between 0 and 265 characters.
Terminator	Indicates the end of the frame. CR: Succeeding frame *CR: No succeeding frame



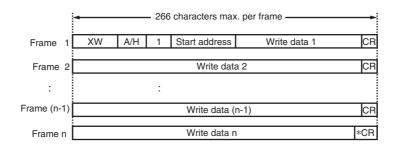


#### Frame Division Method

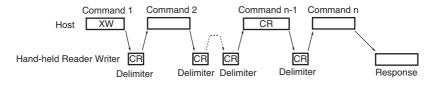
If the command length is longer than 266 characters, divide the data into separate frames before sending as follows:

#### Frame Division Method

- 1. Divide the data into frames each with 266 characters max.
- 2. Use the final terminator (\* CR) for the last frame (frame n) only. Use the delimiter (CR) at the end of other frames.
- 3. Be sure to include the command code, data setting, processing area number setting, and start address in the first frame (frame 1). If any of these parameters is omitted, a command input error will occur. The write data can be omitted.
- 4. Make sure that data is divided correctly without any single frames containing AA\*CR or XZ\*CR.



#### Communications Procedure

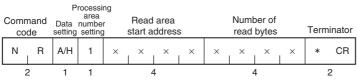




### **EXPANSION DIVIDED AUTO READ (NR)**

This command divides and reads up to 2 Kbytes of data from the Data Carrier when the Hand-held Reader Writer is moved close to the Data Carrier. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended. The host device cannot send commands to the Hand-held Reader Writer until all the responses have been received.

Command



Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 4-digit hexadecimal.  The maximum number of bytes that can be read at one time is 2,048 bytes.  Setting range: 0001h to 0800h  •ASCII: 2,048 bytes (2,048 characters)  •Hexadecimal code: 2,048 bytes (4,096 characters)

Response

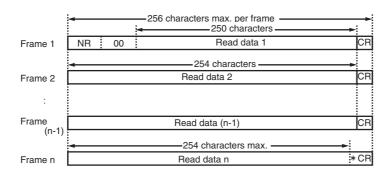
When the read data is within 250 characters.



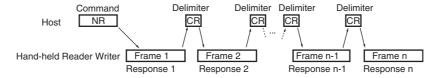
End code	Indicates the execution result for the command.  The end code 00 indicates normal completion.
	For details on end codes, refer to End code List.  p.101
Read data	Indicates the data read from the Data Carrier.  The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.

When the read data is 251 characters or higher.

The data received from the host device is divided into frames according to the delimiters (CR), as shown in the following diagram.



#### Communications Procedure





### **EXPANSION DIVIDED AUTO WRITE (NW)**

This command divides and writes up to 2 Kbytes of data to the Data Carrier when the Hand-held Reader Writer is moved close to the Data Carrier. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended. The host device cannot send commands to the Hand-held Reader Writer until all the responses have been received

Command

#### Frame 1

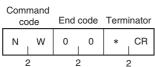


Data setting	Specifies the code format used to send write data to the Data Carrier.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Write area start address	Specifies the start address of the area to be written to in 4-digit hexadecimal.  Setting range: 0000h to 1FFFh
Write data	Indicates the data to be written to the Data Carrier. Data can be between 0 and 257 characters.
Terminator	Indicates the end of the frame. CR: Succeeding frame *CR: No succeeding frame

#### Frames 2 to n



Write data	Indicates the data to be written to the Data Carrier.  Data can be between 0 and 265 characters.
Terminator	Indicates the end of the frame. CR: Succeeding frame *CR: No succeeding frame



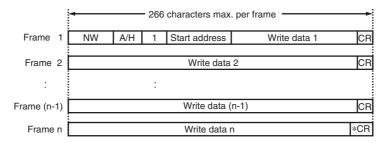
End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to End code List.  p.101

#### Frame Division Method

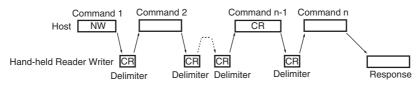
If the command length is longer than 266 characters, divide the data into separate frames before sending, as follows:

#### Frame Division Method

- 1. Divide the data into frames each with 266 characters max.
- 2. Use the final terminator (\* CR) for the last frame (frame n) only. Use the delimiter (CR) at the end of other frames.
- 3. Be sure to include the command code, data setting, processing area number setting, and start address in the first frame (frame 1). If any of these parameters is omitted, a command input error will occur. The write data can be omitted.
- 4. Make sure that data is divided correctly without any single frames containing AA\*CR or XZ\*CR.



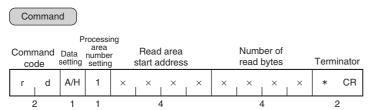
#### Communications Procedure



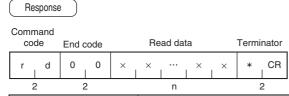


### **EXPANSION BATCH READ (rd)**

This command reads up to 2 Kbytes of data from the Data Carrier in a batch. If the Data Carrier is not in communications range, an error response (end code: 72 = Data Carrier non-existent) will be returned.



Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 4-digit hexadecimal.  The maximum number of bytes that can be read at one time is 2,048 bytes.  Setting range: 0001h to 0800h  •ASCII: 2,048 bytes (2,048 characters)  •Hexadecimal code: 2,048 bytes (4,096 characters)



End code	Indicates the execution result for the command.  The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> . p.101
Read data	Indicates the data read from the Data Carrier. The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.

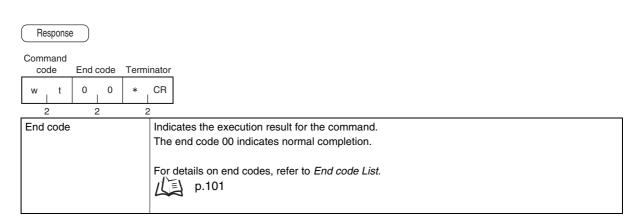
## **EXPANSION BATCH WRITE (wt)**

This command writes up to 2 Kbytes of data to the Data Carrier in a batch. If the Data Carrier is not in communications range, an error response (end code: 72 = Data Carrier non-existent) will be returned.

Command

Processing area number code setting s

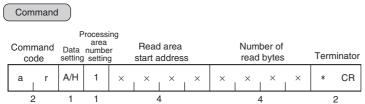
Data setting	Specifies the code format used to send write data to the Data Carrier.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Write area start address	Specifies the start address of the area to be written to in 4-digit hexadecimal.  Setting range: 0000h to 1FFFh
Write data	Indicates the data to be written to the Data Carrier.  The maximum number of bytes that can be written at one time is 2,048 bytes.  Setting range: 0001h to 0800h  *ASCII: 2,048 bytes (2,048 characters)  *Hexadecimal code: 2,048 bytes (4,096 characters)



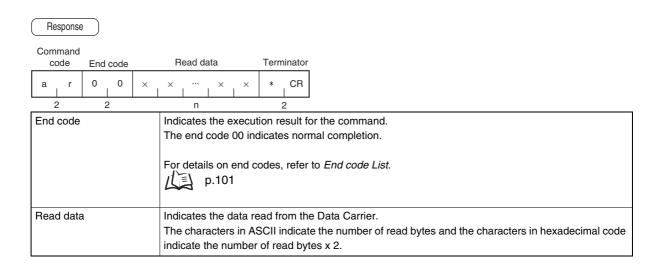


### **EXPANSION BATCH AUTO READ (ar)**

This command reads up to 2 Kbytes of data from the Data Carrier in a batch when the Hand-held Reader Writer moves close to the Data Carrier. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended.

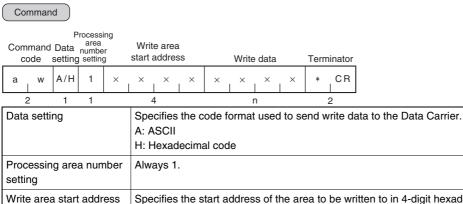


Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 4-digit hexadecimal.  The maximum number of bytes that can be read at one time is 2,048 bytes.  Setting range: 0001h to 0800h  •ASCII: 2,048 bytes (2,048 characters)  •Hexadecimal code: 2,048 bytes (4,096 characters)

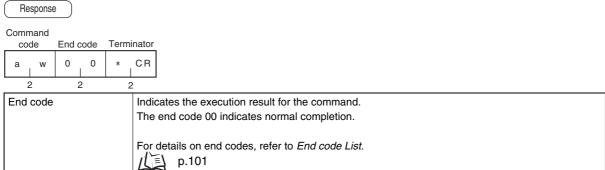


### **EXPANSION BATCH AUTO WRITE (aw)**

This command writes up to 2 Kbytes of data to the Data Carrier in a batch when the Hand-held Reader Writer moves close to the Data Carrier. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended.



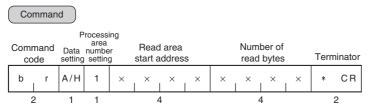
Write area start address	Specifies the start address of the area to be written to in 4-digit hexadecimal.  Setting range: 0000h to 1FFFh
Write data	Indicates the data to be written to the Data Carrier.
	The maximum number of bytes that can be written at one time is 2,048 bytes.
	Setting range: 0001h to 0800h
	•ASCII: 2,048 bytes (2,048 characters)
	•Hexadecimal code: 2,048 bytes (4,096 characters)





### **EXPANSION BATCH BUTTON READ (br)**

After this command is received by the Hand-held Reader Writer, up to 2 Kbytes of data will be read from the Data Carrier in a batch when the activate switch is pressed. If the activate switch is pressed and the Data Carrier is not in communications range, an error response (end code: 72 = Data Carrier non-existent) will be returned.



Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 4-digit hexadecimal.  The maximum number of bytes that can be read at one time is 2,048 bytes.  Setting range: 0001h to 0800h  •ASCII: 2,048 bytes (2,048 characters)  •Hexadecimal code: 2,048 bytes (4,096 characters)

Comi	nana de	End o	code		Re	ad da	ta		Termi	nator
b	r	0	0	×	×		×	×	*	CR
	2	- 2	2			n			- 2	2

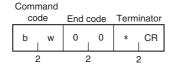
End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> .
Read data	Indicates the data read from the Data Carrier.  The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.

## **EXPANSION BATCH BUTTON WRITE (bw)**

After this command is received by the Hand-held Reader Writer, up to 2 Kbytes of data will be written to the Data Carrier in a batch when the activate switch is pressed. If the activate switch is pressed and the Data Carrier is not in communications range, an error response (end code: 72 = Data Carrier nonexistent) will be returned.



Data setting	Specifies the code format used to send write data to the Data Carrier.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Write area start address	Specifies the start address of the area to be written to in 4-digit hexadecimal.  Setting range: 0000h to 1FFFh
Write data	Indicates the data to be written to the Data Carrier.  The maximum number of bytes that can be written at one time is 2,048 bytes.  Setting range: 0001h to 0800h  •ASCII: 2,048 bytes (2,048 characters)  •Hexadecimal code: 2,048 bytes (4,096 characters)



End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> .  p.101



### **EXPANSION BATCH BUTTON AUTO READ (ur)**

After this command is received by the Hand-held Reader Writer, up to 2 Kbytes of data will be read from the Data Carrier in a batch when the activate switch is pressed after the Hand-held Reader Writer moves close to the Data Carrier. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended.





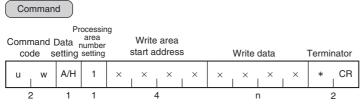
Data setting	Sets the code format used to send responses for read data.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Read area start address	Specifies the start address of the area in the Data Carrier to be read from in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
Number of read bytes	Specifies the number of bytes to be read from the Data Carrier in 4-digit hexadecimal.  The maximum number of bytes that can be read at one time is 2,048 bytes.  Setting range: 0001h to 0800h  •ASCII: 2,048 bytes (2,048 characters)  •Hexadecimal code: 2,048 bytes (4,096 characters)



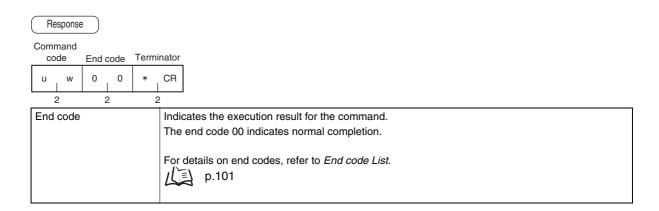
End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> . p.101
Read data	Indicates the data read from the Data Carrier.  The characters in ASCII indicate the number of read bytes and the characters in hexadecimal code indicate the number of read bytes x 2.

### **EXPANSION BATCH BUTTON AUTO WRITE (uw)**

After this command is received by the Hand-held Reader Writer, up to 2 Kbytes of data will be written to the Data Carrier in a batch when the activate switch is pressed after the Hand-held Reader Writer moves close to the Data Carrier. The Hand-held Reader Writer responds when communications between the Hand-held Reader Writer and Data Carrier have ended.



Data setting	Specifies the code format used to send write data to the Data Carrier.  A: ASCII  H: Hexadecimal code
Processing area number setting	Always 1.
Write area start address	Specifies the start address of the area to be written to in 4-digit hexadecimal.  Setting range: 0000h to 1FFFh
Write data	Indicates the data to be written to the Data Carrier.  The maximum number of bytes that can be written at one time is 2,048 bytes.  Setting range: 0001h to 0800h  •ASCII: 2,048 bytes (2,048 characters)  •Hexadecimal code: 2,048 bytes (4,096 characters)





The Data Carrier's memory data and calculation data is calculated in hexadecimal and the result is written to the Data Carrier. If an overflow during addition or underflow during subtraction occurs, the data will not be written and an error response (end code: 76 = Data check error) will be returned.

Command Processing Number of area Calculation area calculation Command Data code setting number start address Calculation data Terminator area bytes code setting A/S  $\mathsf{CR}$ W 2 2 Specified number of bytes

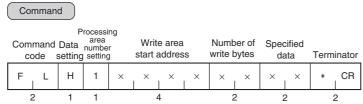
Processing specification	Specifies the calculation method.  A: Add hexadecimal  S: Subtract hexadecimal
	O. Gubilati fickadeoiffal
Processing area number setting	Always 1.
Calculation area start address	Specifies the start address of the area to be written to in 4-digit hexadecimal.  Setting range: 0000h to 1FFFh
Number of calculation area bytes	Specifies the number of bytes in the area for calculating data in 2-digit hexadecimal.  Setting range: 01h to 04h
Calculation data	Specifies the numerical values to be calculated in hexadecimal.

Response Command Calculation data End code code Terminator С 0 0 CR W 2 2 Specified number of bytes 2

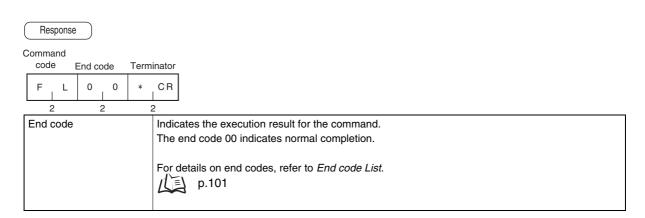
Calculation data	Returns the calculation result data written to the Data Carrier.
	If an overflow during addition or underflow during subtraction occurs, the end code 76 (data check
	error) will be returned. The data prior to the calculation will not be added to the response.

### FILL (FL)

This command writes one byte of specified data to the specified memory area of the Data Carrier. The write data is specified in hexadecimal.



Data setting	Always H.
Processing area number setting	Always 1.
Write area start address	Specifies the start address of the area in the Data Carrier to be written to in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
Number of write bytes	Specifies the data to be written to the Data Carrier in 2-digit hexadecimal.  Setting range: 00h to FFh (00 = 256 bytes)
Specified data	Indicates the data to be written to the Data Carrier.



#### •Example

Writing 01H to the 06H bytes in the memory area starting from address 0030H for a Data Carrier in which the same data and address is written.

Comman	nd											
Command code	Data	Proces area numbe settino	r	Write start ac			Numb write	per of bytes	Specif data		Term	ninator
F L	Н	1	0	0	3	0	0	6	0	1	*	CR
2	1	1		4			2	2	2			2
Response	е											
Command code	End	code	Tern	ninator								

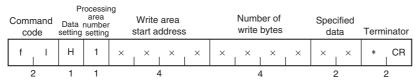
	Before I	Writing
002FH	2	F
0030H	3	0
0031H	3	1
0032H	3	2
0033H	3	3
0034H	3	4
0035H	3	5
0036H	3	6

	After V	Writing
002FH	2	F
0030H	0	1
0031H	0	1
0032H	0	1
0033H	0	1
0034H	0	1
0035H	0	1
0036H	3	6

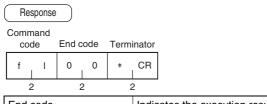


This command writes specified data for the number of write bytes starting from the specified write start address. Up to 2 Kbytes of data can be written in a batch.

Command



Data setting	Always H.
Processing area number setting	Always 1.
Write area start address	Specifies the start address of the area in the Data Carrier to be written to in 4-digit hexadecimal code.  Setting range: 0000h to 1FFFh
Number of write bytes	Specifies the data to be written to the Data Carrier in 4-digit hexadecimal.  Setting range: 0001h to 0800h
Specified data	Indicates the data to be written to the Data Carrier.



End code	Indicates the execution result for the command. The end code 00 indicates normal completion.
	For details on end codes, refer to <i>End code List</i> .  p.101

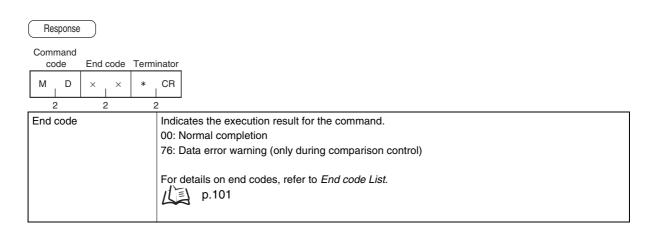


### DATA CHECK (MDC/K)

This command writes or compares the CRC code using the specified check block unit. The CRC code is calculated from the generated polynomial expression  $X^{16}$  +  $X^{12}$  +  $X^5$  + 1.

Command Processing Command Process number code setting setting Check block Number of check block bytes Terminator start address

Process setting	Specifies the check process. K: Check code calculation
	C: Check code calculation C: Check code comparison
Processing area number setting	Always 1.
Check block start address	Specifies the start address of the check block in 4-digit hexadecimal.  Setting range: 0000h to 1FFDh
Number of check block bytes	Specifies the number of bytes in the check block in 2-digit hexadecimal.  Setting range: 00h, 03h to FFh (00 = 256 bytes)
	The number of check block bytes is the check code calculation area + 2 bytes. For details, refer to Memory Check Function in Data Carrier.  p.114

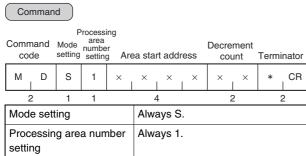




For details on the memory check, refer to Memory Check Function in Data Carrier.

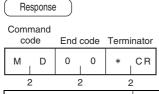
### **OVERWRITE COUNT CONTROL (MDS)**

This command is used to control the number of overwrite operations performed by EEPROM Data Carriers. This command determines whether the EEPROM overwrite count has been exceeded when the specified number of overwrites is subtracted from the specified overwrite count control area data.



Processing area number setting	Always 1.
Area start address	Specifies the start address of the overwrite count control area in 4-digit hexadecimal.  Setting range: 0000h to 1FFDh
Decrement count	Specifies the number of refresh operations in 2-digit hexadecimal.  Setting range: 00h to FFh (00 = Performs overwrite count check only)  For details, refer to Data Carrier Service Life Detection.  p.111

Set the start address between and and and set the start address is set between DDGH and DDTH or between DDH and DDFH, an address error (error code: 7A(HEX)) will be returned in the end code. CHECK!



End code	Indicates the execution result for the command.
	00: Normal completion
	76: Data error warning
	For details on end codes, refer to End code List. p.101

For details on controlling the overwrite count, refer to Data Carrier Service Life Detection.

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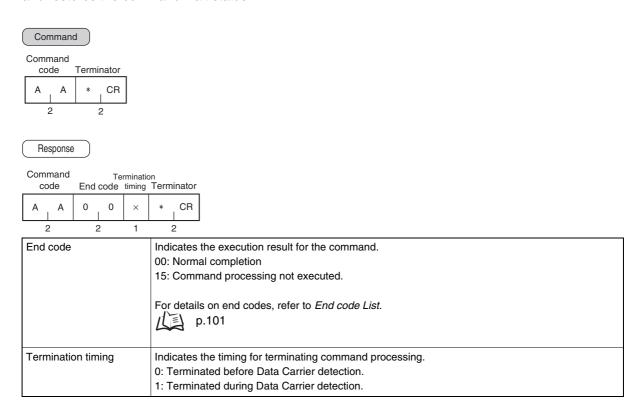
### **Communications Subcommands**

Communications subcommands are used together with communications commands. Communications with the Data Carrier cannot be performed using only these subcommands.



#### **COMMAND PROCESSING TERMINATE (AA)**

Terminates the processing of the communications commands and error noise detection commands, and restores the command wait status.



#### **Host Commands**

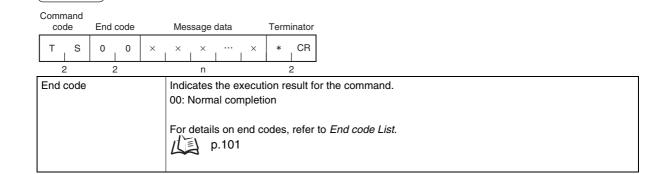
### TEST (TS)

Response

This command returns test messages sent from the host device without changing anything.

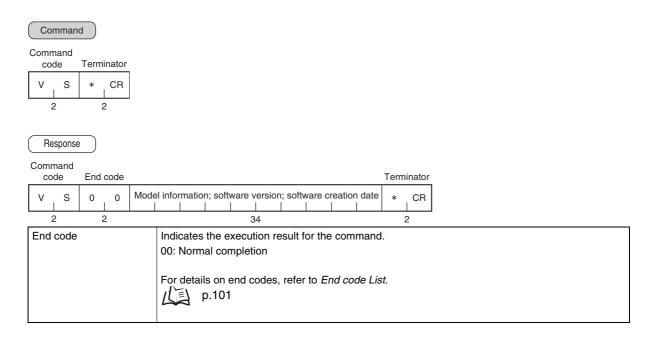
The TEST command is used for communications tests between the host device and the Hand-held Reader Writer.





### **VERSION READ (VS)**

Reads the Hand-held Reader Writer's model information, software version, and software creation date.



### **Controller Control Commands**

These commands are used to reset the Controller or set serial communications.



### **ABORT (XZ)**

This command is used to restore the Hand-held Reader Writer to command wait status when there is no response from the Hand-held Reader Writer due to some problem during communications with the host device or with a Data Carrier.



The ABORT (XZ) command can be used only with the V600-CH1D-V2.

Do not use it with the V600-CHUD.



Command Terminator

Response

None

# **COMMUNICATIONS CONDITIONS SETTING (TR)**

This command is used to set serial communications parameters. The Hand-held Reader Writer must be restarted to make the changes take effect.

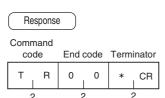
CHECK!

The COMMUNICATIONS CONDITIONS SETTING (TR) command can be used only with the V600-CH1D-V2. Do not use it with the V600-CHUD.

Command

Command code				Data length			Term	inator
Т		R	1	1	1	1	*	CR
2		1	1	1	1	2	2	

Baud rate	Sets the baud rate.
	0: 9,600 bps
	1: 2,400 bps
	2: 4,800 bps
	3: 19,200 bps
	4: 38,400 bps
	Default setting: 9,600 bps
Data length	Sets the data length.
	0: 7 bits
	1: 8 bits
	Default setting: 7 bits
Parity	Sets the parity.
	0: Even parity
	1: Odd parity
	2: No parity
	Default setting: Even parity
Stop bits	Sets the number of stop bits.
	0: 2 bits
	1: 1 bit
	Default setting: 2 bits



End code	Indicates the execution result for the command. 00: Normal completion
	For details on end codes, refer to <i>End code List</i> .  p.101



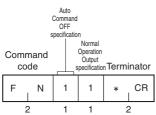
### **BASIC FUNCTIONS SETTING (FN)**

This command is used to set the Auto Commands OFF function and Normal Operation Output function. The Hand-held Reader Writer must be restarted to make the changes take effect.

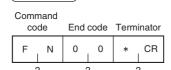


Only the Auto Command OFF function is supported by the V600-CHUD. The Normal Operation Output function is not supported by the V600-CHUD.

#### Command



Auto Command OFF specifications	Designates whether the Auto Command OFF function is used.  0: Auto Command OFF used.  1: Auto Command OFF not used.  Default setting: Auto Command OFF used.
Normal Operation Output Specification	Designates whether the Normal Operation Output is used. 0: Normal Operation Output used. 1: Normal Operation Output not used. Default setting: Normal Operation Output used.



End code	Indicates the execution result for the command.  00: Normal completion
	For details on end codes, refer to <i>End code List</i> .  p.101

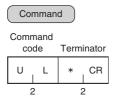
### **SET INFORMATION READ (UL)**

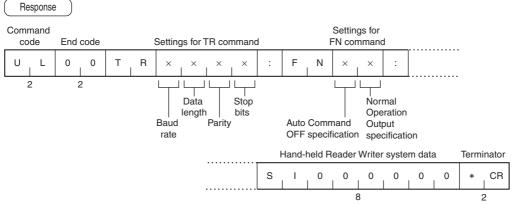
This command is used to read the settings of the Hand-held Reader Writer.



Only the Auto Command OFF function is supported by the V600-CHUD.

The settings made with the COMMUNICATIONS CONDITIONS SETTING (TR) command are not valid for the V600-





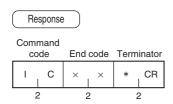
End code	Indicates the execution result for the command.					
	00: Normal completion					
	For details on end codes, refer to <i>End code List</i> .  p.101					
Settings for TR command	Baud rate	0: 9,600 bps				
		1: 2,400 bps				
		2: 4,800 bps				
		3: 19,200 bps				
		4: 38,400 bps				
	Data length	0: 7 bits				
		1: 8 bits				
	Parity	0: Even parity				
		1: Odd parity				
		2: No parity				
	Stop bits	0: 2 bits				
		1: 1 bit				
Settings for FN command	Auto Command OFF Specification	0: Auto Command OFF used.				
		1: Auto Command OFF not used.				
	Normal Operation Output Specification	0: Normal Operation Output used.				
		1: Normal Operation Output not used.				
System data	SI000000					

### **Other Commands**



### **UNDEFINED COMMAND RESPONSE (IC)**

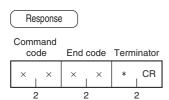
This command is returned as the response when the Hand-held Reader Writer cannot read the command header.





### **Error Response**

If an error occurs during communications with the host device, or the Data Carrier, error notification is provided in the end code.



### **End code List**

End codes are indicated in 2-digit hexadecimal code.

Status	End code	Meaning
Normal	00	Normal completion
	7B	Battery low warning indicating that battery replacement is required (See note 1.)
Host communications error	10 (See note 2.)	Vertical parity error
	11 (See note 2.)	Framing error
	12 (See note 2.)	Overrun error
	14	Format error
	15	Execution status error
	18	Frame length error
Lower communications error	70	Data Carrier communications error
	71	Mismatch error
	72	Data Carrier non-existent error
	76	Data error
	7A	Address error
	7C	Antenna error
	7D	Write protect error
Memory error	93 (See note 2.)	EEPROM memory error

- Note 1: A 7B error code response indicates that the command was completed normally, but the battery voltage is low. And the operation indicator will be lit red. If the battery voltage is so low that a response cannot be returned, an error code such as 72 will be returned.
  - 2: Vertical parity errors, framing errors, and overrun errors do not occur for the V600-CHUD.



For details on each error, refer to Error Tables.

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MEMO

## **Section 4 Functions**

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## **Hand-held Reader Writer Functions**



The Hand-held Reader Writer can read and write across several non-consecutive Data Carrier memory areas (10 areas max.) at one time. To use this feature, the number of control areas is specified using the NUMBER OF CONTROL AREAS command. ASCII and hexadecimal code can be used simultaneously for the one command control, but reading and writing cannot be performed simultaneously.

Example: Data in the Following 3 Areas are Read

Area (1):	Address	0010H
	Number of bytes	05 bytes
	Code setting	ASCII
Area (2):	Address	0030H
	Number of bytes	02 bytes
	Code setting	Hexadecimal
Area (3):	Address	0035H
	Number of bytes	03 bytes
	Code setting	Hexadecimal

	0010H	4	F	"O"
	0011H	4	D	"M"
Area (1)	0012H	5	2	"R"
	0013H	4	F	"O"
	0014H	4	Е	"N"
	_			
. (2)	0030H	1	2	
Area (2)	0031H	3	4	
	_			
	0035H	3	1	
Area (3)	0036H	3	2	
	0037H	3	3	
				l

Command RDA3001005H003002H003503\* CR RD000MRON1234313233\* CR Area (1) Area (2) Area (3)



Refer to Command and Response Format for more details on ASCII and hexadecimal codes.

#### **Auto Command OFF Function**

If communications with the Data Carrier do not begin within one minute after an auto command or button auto command is sent from the host device to the Hand-held Reader Writer after entering the Data Carrier wait status, the Auto Command OFF function automatically aborts the auto command and returns a "Data Carrier non-existent" error (error code 72) to the host device. When the Auto Command OFF function is not used, the auto command will not be aborted even if one minute passes after entering the Data Carrier wait status.

This function is set using the BASIC FUNCTIONS SETTING (FN) command.



Refer to the section on the BASIC FUNCTIONS SETTING (FN) command for details on the setting method.





### **Normal Operation Output Function**

When the Hand-held Reader Writer is operating normally, this function turns ON the Data Set Ready (DS) output to allow the host device to monitor the operating status of the Hand-held Reader Writer. This function is set using the BASIC FUNCTIONS SETTING (FN) command.



The Normal Operation Output function cannot be used with the V600-CHUD. Refer to section on the BASIC FUNCTIONS SETTING (FN) command for details on the setting method.



#### **Data Carrier**

The memory access space available to the Hand-held Reader Writer is 0000H to 1FFFH, totaling 8 Kbytes. The available access space is determined by the Data Carrier memory capacity. The allocations for the Hand-held Reader Writer's manufacturing date area, write-protect area, and control methods for these areas depend on the type of Data Carrier memory used (SRAM or EEPROM).



For details on the Data Carrier, refer to the Appendices or the *Read/Write Head and Data Carrier Manuals* (Cat. No. Z127-E1, Z128-E1).





#### **Manufacturing Date Format (Default Setting)**

#### Using SRAM (Built-in Battery) Data Carrier

The date of manufacture is registered in the first 2 bytes of the memory area, which control the Data Carrier battery life. This area can be read, but cannot be written to by the user. If a writing operation mistakenly occurs, an error (error code: 7D) will result.

#### Manufacturing Date Area

Address	Bit	7	6	5	4	3	2	1	0
0000		Second digit of month			First digit of month				
0001			Second digit of year			First digit of year			of

- Note 1. The year of manufacture is represented by the last two digits of the year (for example, "92" for 1992).
  - 2. The month of manufacture is represented by two digits (for example, "03" for March and "10" for October).
  - 3. Years from 2000 onwards are represented beginning with 00 (for example, "0400" for April 2000 and "1204" for December 2004).

#### Example: Manufacturing Date of September 1992

Address E	Bit	7	6	5	4	3	2	1	0
0000		0	0	0	0	1	0	0	1
0001		0				9			
		1	0	0	1	0	0	1	0
0001		9				2			

#### Using EEPROM (Without Battery) Data Carrier

There is no manufacturing date area. The start address is a write-protected area.



### Write Protect Function

The write protect function prevents important data stored in the Data Carrier, such as the product type and model, from being overwritten by other data and lost. Use the following methods to set write protection after writing important data.

### •EEPROM Data Carriers (without Battery)

#### Setting the Write Protect Function

The write protect function is set by writing the final address to be protected in address 0000H of the Data Carrier's memory. The area between address 0001H and the write-protect end address will be write-protected. The status of the most significant bit of address 0000H determines whether or not the write protect function is in effect.

Address	Bit	7	6	5	4	3	2	1	0
0000		Yes/ No							

- •Write-protect Bit (Most significant bit of address 0000H)
  - 1: Write-protected (Yes)
  - 0: Not write-protected (No)
- End address setting range

00H, 01H to 7FH

Address 0080H to 00FFH can therefore not be set as the end address. If the end address is set to 00H, however, all addresses from 0001H to 00FFH will be protected.

### Write-protect Setting Examples (254-byte Memory Data Carrier)

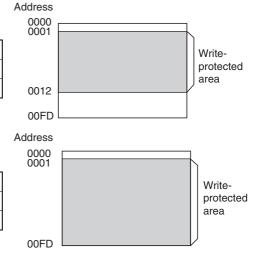
### (1) The following settings would write-protect addresses 0001H through 0012H:

Address	Bit	7	6		4	2	2	1	0
Address	DIL	_ ′	6	5	4	3			U
0000	1	0	0	1	0	0	1	0	
0000			ç	9			2	2	

(2) The entire memory except address 0000H is writeprotected by setting the end address to 00H, as shown below.

(Example: When the end address is 00H)

Address	Bit	7	6	5	4	3	2	1	0
0000		1	0	0	0	0	0	0	0
0000			8	3			(	)	



#### Canceling Write Protection

To cancel write protection, turn OFF the most significant bit of address 0000H. The write protection will be cancelled, and the address set in 0000H will be ignored.



Address 0000H is the write protection setting area. Therefore, always structure the data so that any data that needs to be write protected is written in addresses starting from 0001H.

### •SRAM Data Carriers (with Built-in Battery)

### **Setting Write Protect Function**

The write protect function is set in the four bytes of addresses 0002H through 0005H of the Data Carrier's memory. The status of the most significant bit of address 0002H determines whether or not the write protect function is enabled.

Address	Bit	7	6	5	4	3	2	1	0
0002		Yes/ No	Ul	pper t	wo dig	gits of	start	addre	ss
0003		Lower two digits of start address							
0004		Upper two digits of end address							
0005			Low	er two	digits	of er	id add	Iress	

- •Write-protect Bit (most significant bit of address 0002H)
  - 1: Data is write-protected
  - 0: Data is not write-protected
- •Write Protect Setting Area

Start address: 0006H to 1FFFH End address: 0006H to 1FFFH

### Settings to write-protect addresses 0006H through 07FFH

Address Bit		Uppe	r digit			Lowe	r digit	
0002	1	0	0	0	0	0	0	0
		8	3		0			
0003	0	0	0	0	0	1	1	0
		(	)		6			
0004	0	0	0	0	0	1	1	1
0004		(	)		7			
0005	1	1	1	1	1	1	1	1
0005		F	=	•	F			

### Settings to not write-protect addresses

Address Bit		Uppe	r digit			Lowe	r digit	
0002	0	0	0	0	0	0	0	0
		(	)		0			
0003	0	0	0	0	0	1	1	0
		(	)		6			
0004	0	0	0	0	0	1	1	1
0004		(	)		7			
0005	1	1	1	1	1	1	1	1
		F				F		

### **⚠** WARNING

The SRAM Data Carrier has a built-in lithium battery that can ignite, combust, or explode if mishandled, which may occasionally result in serious injury. Do not disassemble, pressurize, or deform the Data Carrier, subject it to high temperatures (of 100°C or more), or dispose of it by incineration. Dispose of the Data Carrier as industrial waste.

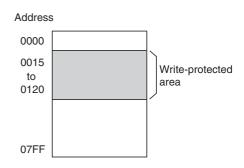


### Write Protect Setting Examples (2-Kbyte Memory Data Carrier)

#### (1)Settings to Write-protect Addresses 0015H to 0120H

(Start address < End address)

									-
Address \ Bi	t 7	6	5	4	3	2	1	0	
,	1	0	0	0	0	0	0	0	
0002		•							(Hexa-
			3	)		deci- mal)			
									maij
0003	0	0	0	1	0	1	0	1	
0000		1				į			
0004	0	0	0	0	0	0	0	1	
0004		0							
0005	0	0	1	0	0	0	0	0	
5005		2				(			



#### (2)Settings to Write-protect 1 Byte

(Start address = End address)

Specify the same address for the start and end addresses.

## (3)Settings when the End Address is Greater than the Final Address in the Data Carrier

(End address > 07FFH)

The Data Carrier memory area is allocated from address 0000H to 07FFH. Therefore, the addresses up to 07FFH will be write-protected.

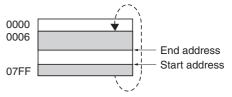
## (4)Settings when the Start Address is Greater than the End Address

(Start address > End address)

The area between 0006H and the end address and the area between the start address and 07FFH are write-protected.

# 1 byte Write-protected area





#### Canceling Write Protection

To cancel write protection, turn OFF the most significant bit of address 0002H. The write protection will be cancelled, and the start and end addresses that are set for 0002H to 0005H will be ignored.



### **Data Carrier Service Life Detection**

The methods used to detect the service life of the Data Carrier depend on the memory type (SRAM or EEPROM). For SRAM, a battery life check is performed, and for EEPROM, the number of overwrites is monitored.

### SRAM Data Carriers (with Built-in Battery)

### Checking If the Battery is Low

Built-in Battery (Not Including V600-D2KR16)

(1)A battery-low check for the Data Carrier can only be performed when special access is made. The battery-low check is performed by running a fixed current through the internal circuit of the Data Carrier. If the battery-low check is performed every time access is made, battery power is also consumed. It is recommended that this be included as a routine check, once a day, when creating system programs.

(2) The access method for performing a battery-low check can only be performed when the two bytes of data from addresses 0000H to 0001H are read. Execute one of the following commands to perform a battery-low check.

#### Battery-low Check Commands

a. READ command	RD H/A1 0000 02*CR
b. AUTO READ command	AR H/A1 0000 02*CR
c. BUTTON READ command	BR H/A1 0000 02*CR
d. BUTTON AUTO READ command	UR H/A1 0000 02*CR
e. COPY READ command	RC H/A1 0000 0002*CR
f. EXPANSION DIVIDED READ command	XR H/A1 0000 0002*CR
g. EXPANSION DIVIDED AUTO READ command	NR H/A1 0000 0002*CR
h. EXPANSION BATCH READ command	rd H/A1 0000 0002*CR
i. EXPANSION BATCH AUTO READ command	ar H/A1 0000 0002*CR
j. EXPANSION BATCH BUTTON READ command	br H/A1 0000 0002*CR
k. EXPANSION BATCH BUTTON AUTO READ command	ur H/A1 0000 0002*CR

#### (3) Response for Low Battery

When the battery is low, 7B is given in the end code section within the response format. The operation indicator will be lit red.

#### Example Normal **Battery Low** RD 00 0995 \*CR RD 7B 0992 \*CR AR 00 0995 \*CR AR 7B 0992 \*CR Read data Normal Read data Battery low Manufactured Manufactured end code error code September 1992 September 1995

•A battery low check is performed for V600-D2KR16 Data Carriers with replaceable batteries when the READ/WRITE commands are executed, regardless of the addresses.

### Data Carrier Life after Low Battery Signal Occurs

After a battery-low signal is sent, the Data Carrier can be used for approximately one month in the normal operating state. The Data Carrier should be replaced, however, as soon as possible.



The SRAM Data Carrier (except the V600-D2KR16) is equipped with a thionyl chloride lithium battery. A characteristic of the thionyl chloride lithium battery is that the internal resistance of the battery increases when the battery is left unused for several months. If this occurs and a Data Carrier battery-low check is performed, a low battery response may be returned regardless of whether battery life still remains. This is a result of the increased resistance within the battery, and is not due to the battery life expiring. If a Data Carrier has been left for several months after purchase without being used, use the read operation for approx. 10 minutes to activate the battery before use. (Current will flow in the battery and resistance in the battery will return to normal as a result of activating the battery. The life of the battery will hardly be affected.)

When using V600-D2KR16 Data Carriers with replaceable batteries, the Data Carrier can be used for approximately two weeks in the normal operating state. The battery should be replaced, however, as soon as possible.

### EEPROM Data Carrier (without Battery)

The OVERWRITE COUNT CONTROL command (MDS) can determine whether the overwrite count for the EEPROM Data Carrier has been exceeded. By executing the OVERWRITE COUNT CONTROL command, the number of overwrites is decremented from the data in the specified overwrite count control area, and whether the data has exceeded the limits is determined.

Area start address

Upper digit

Middle digit

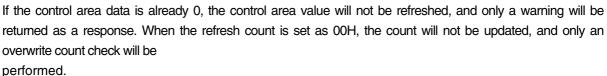
Lower digit

3 bytes

The overwrite count control area consists of 3 bytes from the start address. The decrement value from the overwrite count is written in this area, and if this value is 0 (00H) an end code 76 will be given as a warning. Therefore, to enable control of the number of overwrites, the maximum number of overwrites must be written to the overwrite count control area beforehand.

The user-specified number of overwrites can be set to up to 16,700,000. The number of overwrites in the specifications for EEPROM Data Carriers, however, is 300,000 overwrites (0493E0H) at 40°C max., so be sure to set the number of overwrites to 300,000 or lower.

values, and can be read using the READ command.



For details on command format, refer to REF OVERWRITE COUNT CONTROL (MDS).

The number of overwrites is controlled using hexadecimal

CHECK!

Set the start address to between DDDH and DDH and DDH. If the start address is set between DDGH and DDTH or between DDH and DDFH, an address error (error code: 7A hexadecimal) will be returned as the end code.

(O CHECK!



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### Using the OVERWRITE COUNT Command

Example: When the three bytes from address 0010H are used as the overwrite count area.

1. The overwrite count initial value of 2. Enter the overwrite count of 5. 100,000 times is written in the control area.

"WTH10010"

0010	01н
0011	86н
0012	А0н

"MDS1001005"

A total of 5 times will be decremented from 100,000.

0010	01н
0011	86н
0012	9Вн

3. The accumulated count is 100,000 times.

When "MDS1001000" is executed, it will be "MD76" (overwrite count exceeded.)

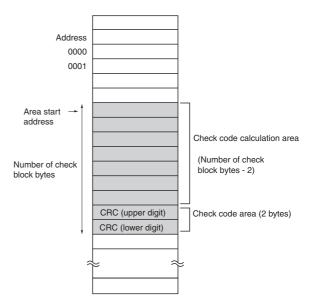
0010	00н
0011	00н
0012	00н



### Memory Check Function in Data Carrier

A memory check can be made using the DATA CHECK command (MDC/K). A CRC (Cyclic Redundancy Check) code calculation, overwrite, and comparison are made, using the check block units specified by the user. The CRC code is calculated from the generated polynomial expression x<sup>16</sup>  $+ x^{12} + x^5 + 1.$ 

The calculation area is the portion of the check block specified by the start address and the number of bytes excluding the last two bytes. The last two bytes are the check code area. check code When write is specified (transaction code: K), the CRC of the calculation area data is calculated and written to the check code area. When data comparison is specified (transaction code: C), the CRC of the calculation area data is calculated and a comparison made with the check code area data. If they coincide, end code 00 is returned, indicating normal transmission, and if they do not coincide, end code 76 is returned as a warning.





For details on the command format, refer to DATA CHECK (MDC/K).

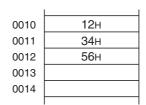


### Example Using the Data Carrier's DATA CHECK Command

In the following example, the data in address 0010H to 0012H is checked.

1. In this example, the following data already exists in 2. Execute MDK1001005 (calculation transaction). the memory. The CRC code 5CD6 calculated from the data 123456 is written to addresses 0013H and

0014H.



0010	12н
0011	34н
0012	56н
0013	5Сн
0014	D6н

3. Execute MDC1001005 (comparison transaction). The normal response MD00 will be returned if the data coincides.

0010	12н		
0011	34н		
0012	56н		
0013	5Сн		
0014	D6н		

If the data error occurs, MD76 (a data error warning) will be returned.

0010	00н	→ Data error
0011	34н	
0012	56н	
0013	5Сн	
0014	D6н	

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## **Section 5 Troubleshooting**

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Non-fatal Errors (Operation Continues)	118
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### **Error Tables**

If an error occurs in the Hand-held Reader Writer, the operation indicator lights or flashes red to notify the type of error.



### **Fatal Errors (Operation Stops)**

If a fatal error occurs, the operation indicator will be lit red and all operations of the Hand-held Reader Writer will stop until the power is turned OFF and then ON again.

Name	Operation indicator	Description
Hardware error	Lit red	Hand-held Reader Writer cannot be operated normally.
Memory error	Lit red	The contents of the backup memory in the Hand-held Reader Writer is corrupted.



### **Non-fatal Errors (Operation Continues)**

If a non-fatal error occurs, the operation indicator will be lit red (or flashing red) and an error code will be returned to the host device.

Name	Operation indicator	Description
Parity error	Flashing red	A parity error has occurred in communications with the host device.
Framing error	Flashing red	A framing error has occurred in communications with the host device.
Overrun error	Flashing red	An overrun error has occurred in communications with the host device.
Format error	Flashing red	The command from the host device was incorrectly formatted.
Frame length error	Flashing red	Command exceeding the maximum frame length was received.
Data Carrier communications error	Lit red	Communications with the Data Carrier could not be performed correctly.
Mismatch error	Lit red	Write control was not performed correctly.
Data Carrier non-existent error	Flashing red	A command that was not an auto command was sent when the Data Carrier was not in the communications area. A command OFF occurred with the auto command.
Address error	Lit red	An address that exceeded the Data Carrier memory area was designated.
Write protect error	Lit red	The manufacturing date area or the write protect area was designated with a WRITE command.



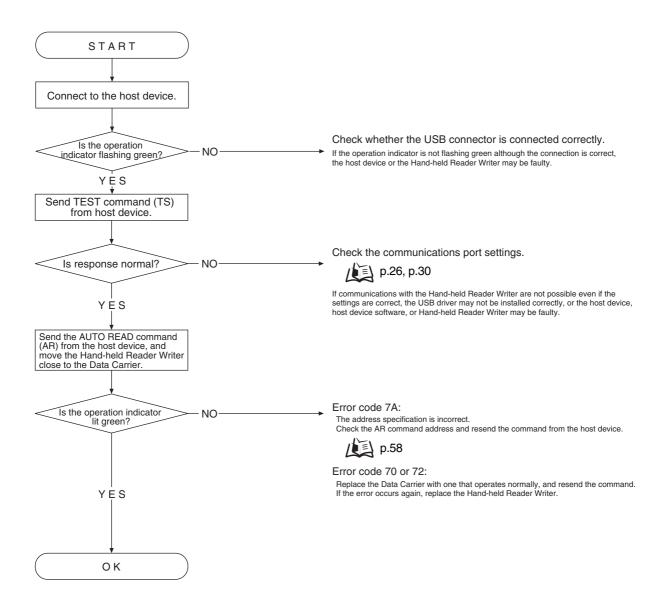
### **Battery low warning**

A 7B error code response indicates that the command was completed normally, but the battery voltage is low.

Name	Operation indicator	Description
Battery low warning	Lit red	Battery low warning indicating that battery replacement is required.

## **Troubleshooting Flowchart**

If an error occurs, be sure to understand the conditions thoroughly, then accurately determine the likelihood of the error re-occurring, whether the problem is related to another device, and other factors causing the error, and refer to the following flowcharts for troubleshooting.



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RFID System User's Manual

## **Section 6 Appendices**

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## **Specifications and Dimensions**

## **General Specifications**

Item	Specification		
item	V600-CHUD	V600-CH1D-V2	V600-CH1D-PSI
Supply voltage	5.0 VDC ±5%		
Ambient operating temperature	−10 to 55°C		
Ambient operating humidity	35% to 85% (with no condensat	ion)	
Ambient storage temperature	-25 to 65°C		
Ambient storage humidity	35% to 85% (with no condensation)		
Degree of protection	IEC60529, IP63 (See note.)		
Weight	Approx. 120 g (with cables and connectors)	Approx. 160 g (with cables and connectors)	Approx. 110 g (with cables and connectors)
Current consumption	250 mA max. (supply voltage: 5.0 V)		
Material	Case: ABS resin; Nameplate: PET resin		
Vibration resistance	10 to 150 Hz, 0.2-mm double amplitude at 15 m/s² acceleration in 6 directions 10 times for 8 minutes each		
Shock resistance	150 m/s² (approx. 15G), 3 times each in 6 directions (up, down, right, left, forward, reverse)		
Insulation resistance	50 M $\Omega$ min. (at 500 VDC) between connector terminals and case		
Dielectric strength	1,000 VAC, 50/60 Hz for 1 min between connector terminals and case (leakage current: 1 mA max.)		
Cable length	0.8 m, 1.9 m	2.5 m	0.8 m

Note: This does not include the connector section. The main unit is not resistant to chemicals or oils.

## **Performance Specifications**

Item	Specification	
Diagnostic function	Checks for CPU errors.	

## V600-A22 Specifications

Item	Specification
Input voltage	100 to 120 VAC at 50/60 Hz
Input current	200 mA±20% (100 VAC) 170 mA±20% (120 VAC)
Output voltage	5 VDC±0.25 V
Ambient operating tem- perature	0 to 40°C
Ambient storage temperature	-40 to 70°C
Ambient storage humidity	25% to 85%
Insulation resistance	100 M $\Omega$ min. (at 500 VDC) between input terminals and output terminals
Dielectric strength	1,500 VAC for 1 min between input terminals and output terminals (leakage current: 5 mA max.)
Weight	Approx. 85 g
Applicable standards	UL and CSA



### **Communications Specifications**

### •Host Communications Interface Specifications

#### V600-CHUD

Item	Specification
Connectors (connector connection status)	Series A plug
USB specifications	Ver 1.1
Baud rate	Full speed (12 Mbps)
Device class	COM class
Vendor ID	Hexadecimal format [0590]
Product ID	Hexadecimal format [0048]



Use the host communications interface as the COM port for the host device.

### V600-CH1D-V2, V600-CH1D-PSI

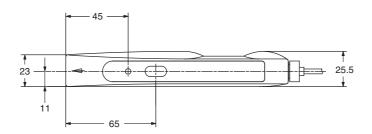
Item	Specification		
item	V600-CH1D-V2	V600-CH1D-PSI	
Connector	D-Sub 9-pin (applicable to IBM PC/AT or compatible) (See note 1.)	D-Sub 9-pin	
Standard compliance	RS-232C		
Transmission line connection	1:1		
Communications method	Two-wire, half duplex		
Synchronization method	Asynchronous (stop bit: 1 or 2) (See note 2.)		
Baud rate	2,400, 4,800, 9,600, 19,200, 38,400 bps (See note 2.)		
Transmission code	7-unit ASCII or 8-unit JIS (See note 2.)		
Communications control	1:1		
Error detection	Vertical parity (even/odd/none) (See note 2.)		

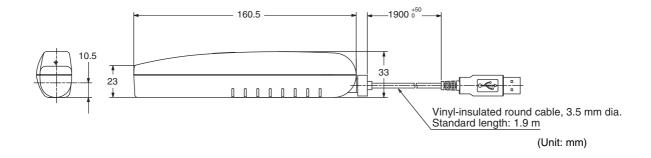
Note 1: For conversion to a 25-pin connector, use the SGC-X9P/25P-2 manufactured by Sunhayato, or an equivalent.

Note 2: Set by a settings command.

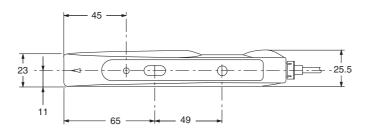
### **Dimensions**

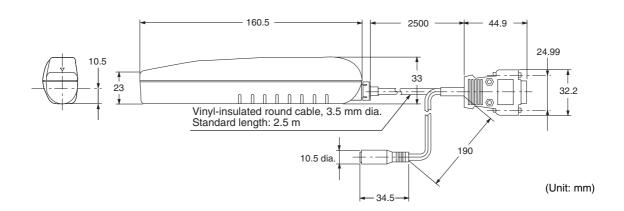
V600-CHUD



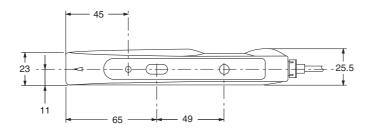


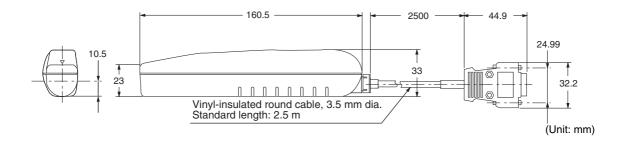
V600-CH1D-V2



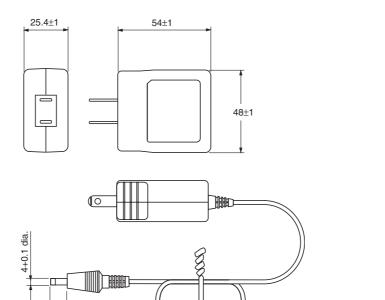


#### V600-CH1D-PSI





#### V600-A22



9.5±0.3

(Unit: mm)



### **Transmission Specifications**

Transmission with the currently available V600-series Data Carriers is possible.

#### Transmission Distances

Data Carrier	Transmission distance
V600-D23P53	0 to 2.5 mm
V600-D23P54	0 to 4 mm
V600-D23P55	0 to 10 mm
V600-D23P61	0 to 11 mm
V600-D23P66N	0 to 17 mm (See note 2.)
V600-D23P66SP	0 to 12 mm
V600-D23P71	0 to 25 mm
V600-D23P72	0 to 23 mm
V600-D8KR04	0 to 35 mm
V600-D8KR12	0 to 25 mm
V600-D8KR13	0 to 20 mm
V600-D2KR16	0 to 10 mm
V600-D8KF04	0 to 18 mm

Note 1: Data Carrier Installation Conditions

V600-D23P53/P54 Embedded in metal (iron).

V600-D23P55 Embedded in resin

V600-D23P61 Metal (iron) on the back surface of the Data Carrier.

V600-D23P66N/P66SP/P71/P72 Resin on the back surface of the Data Carrier. Data Carrier (no metal on back

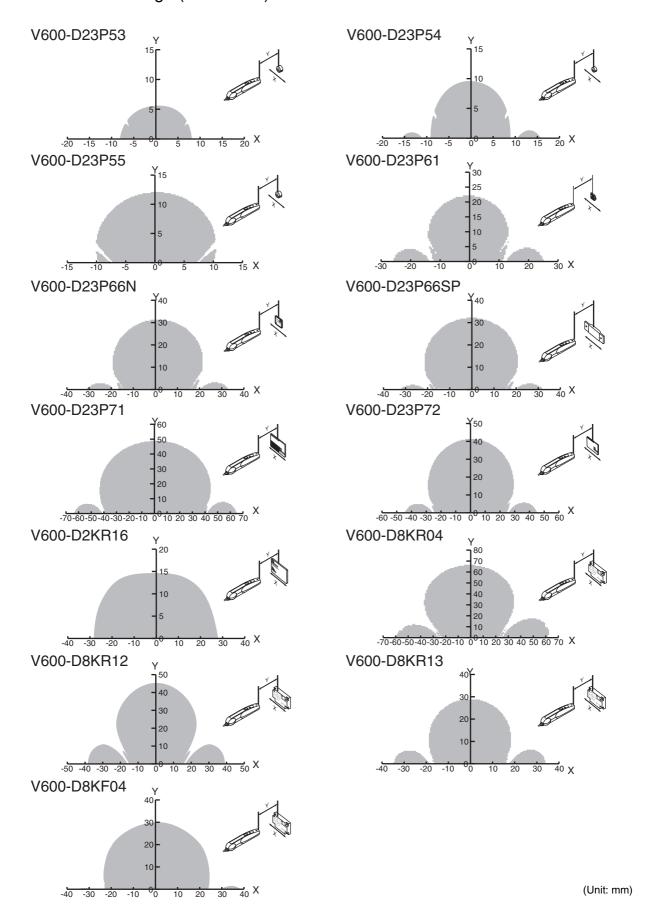
surface)

V600-D8KR04/R12/R13/D8KF04 Metal (iron) on the back surface of the Data Carrier.

V600-D2KR16 Data Carrier installed on a bracket and attached to a metal (aluminium) plate.

Note 2: When using the V600-D23P66N at temperatures of -10°C or lower, transmission may not be possible at the specified distance. In this case, move the Reader Writer slightly further away from the Data Carrier.

### •Transmission Range (Reference)

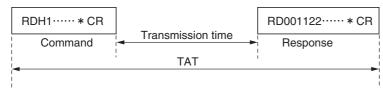




### **Communications Time**

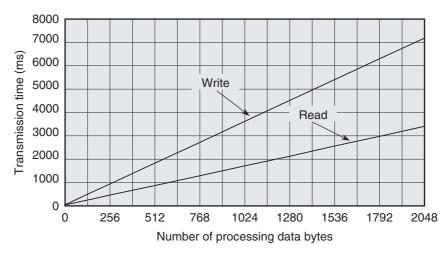
Communications time differs according to the type of Data Carrier memory (SRAM or EEPROM). TAT (Turn Around Time) and transmission time are displayed as communication times. TAT represents the total time from when a command is first sent from the host device until a response is received. The transmission time represents the time required for communications between the Hand-held Reader Writer and the Data Carrier, not including communications with the host device.

#### Example

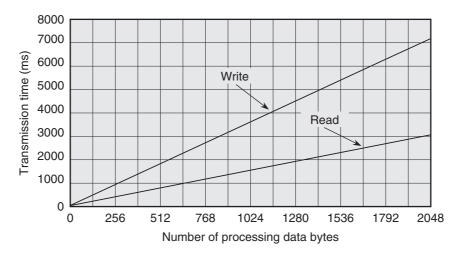


### SRAM Data Carrier (Reference)

#### •TAT



#### Transmission Time



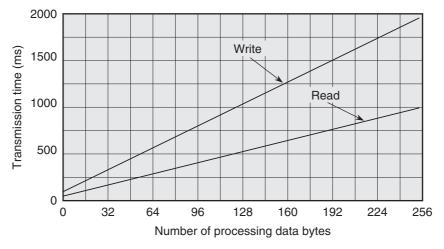
#### Calculation Method

Operation	Transmission time (ms)
Read	T=1.5N+36.7
Write	T=3.5N+51.2

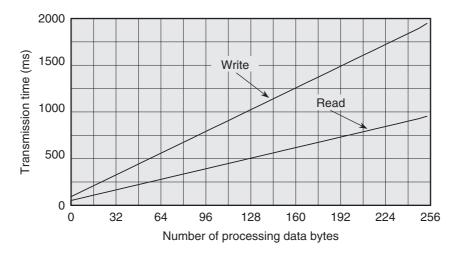
N: Number of processing data

### •EEPROM Data Carrier (Reference)

### •TAT



### •Transmission Time



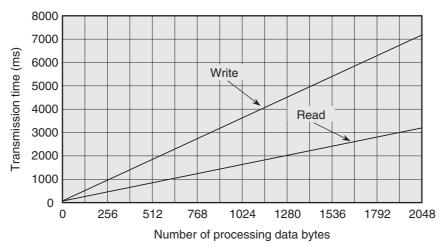
#### Calculation Method

Calculation Motifica							
Operation	Transmission time (ms)						
Read	T=3.6N+53.7						
Write	T=7.3N+90.3						

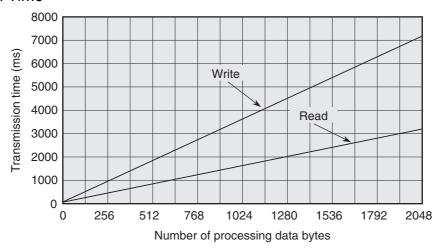
N: Number of processing

### •Fe-RAM Data Carrier (Reference)

### •TAT



### •Transmission Time



#### Calculation Method

Operation	Transmission time (ms)
Read	T=1.5N+61.0
Write	T=3.5N+75.1

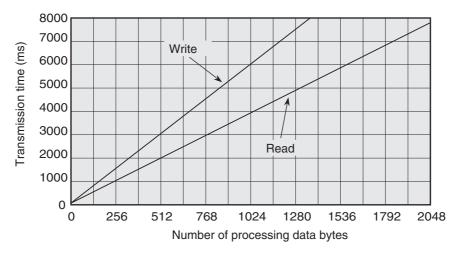
N: Number of processing

Note: The number of TAT data bytes represents the number of bytes when ASCII code is specified.

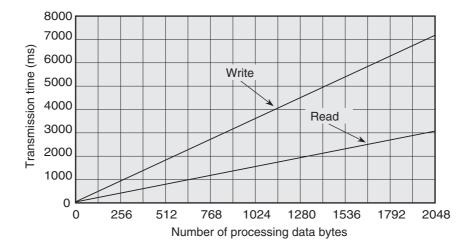
#### V600-CH1D-V2

### •SRAM Data Carrier (Reference)

### •TAT



### •Transmission Time



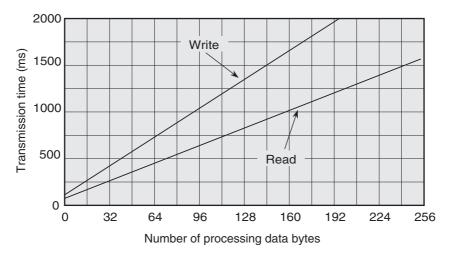
### Calculation Method

Operation	Transmission time (ms)
Read	T=1.5N+37.0
Write	T=3.5N+51.3

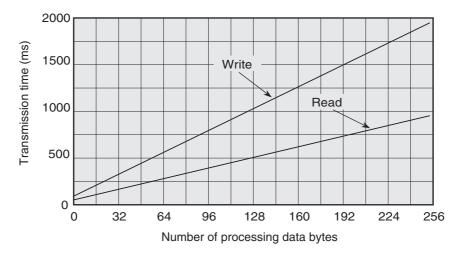
N: Number of processing

### •EEPROM Data Carrier (Reference)

### •TAT



### •Transmission Time



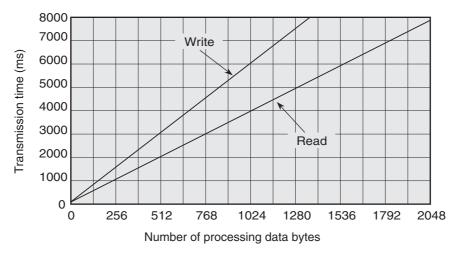
#### Calculation Method

Operation	Transmission time (ms)
Read	T=3.8N+61.2
Write	T=5.8N+69.9

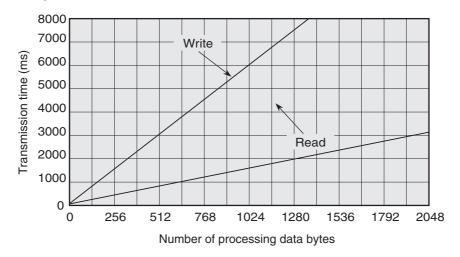
N: Number of processing

### •Fe-RAM Data Carrier (Reference)

#### •TAT



#### •Transmission Time



#### Calculation Method

Calculation Motifica							
Operation	Transmission time (ms)						
Read	T=1.5N+61.6						
Write	T=3.5N+75.8						

N: Number of processing

Note 1: Communications specifications for TAT data with the host device represent values with a baud rate of 9,600 bps, a bit length of 7 bits, 2 stop bits, and even parity. In this example, characters are sent consecutively, with no spaces between them.

Note 2: The number of bytes in the TAT data is the number for ASCII encoding.

## **Data Carrier Memory Map**

### •Data Carrier (Memory ≤ 256 Bytes)

	Address	Data
	0000	Write protect setting area
	0001	
	0002	
	0003	
	:	User area
	:	
	:	
1		1 byte

### •Data Carrier (Memory > 256 Bytes)

Address	← Data →
0000	Manufacturing data area
0001	Manufacturing date area
0002	
\$	Write protect setting area
0005	
0006	
\$	\$
00FF	
0100	
\$	\$
01FF	
	1 byte

For more information on Data Carrier memory capacity and memory type, refer to Data Carrier Memory Capacity and Data Type (V600 Series).

## **Data Carrier Memory Capacity and Data Type (V600 Series)**

(As of September 1999)

Model	Memory capacity (user memory)	Memory type	Life expectancy					
V600-D8KR12			5 years (-25 to +70°C)					
V600-D8KR13	2 Kbytes	S-RAM	8 years (-25 to +70°C)					
V600-D8KR04								
V600-D2KR16	2 Kbytes	SRAM (replace- able battery)	2 years (+25°C)					
V600-D23P53								
V600-D23P54								
V600-D23P55			•Overwrite operations: 100,000 times					
V600-D23P61	054 h. da	FEDDOM	(300,000 times at operating temperature between lower					
V600-D23P71	254 bytes	EEPROM	limit and 40 °C)					
V600-D23P72			•Data retention: 10 years					
V600-D23P66N								
V600-D23P66SP								
V600-D8KF04	8 Kbytes	Fe-RAM	Overwrite operations: 1,000,000,000 times  Data retention: 10 years					

## **MARNING**

The SRAM Data Carrier has a built-in lithium battery that can ignite, combust, or explode if mishandled, which may occasionally result in serious injury. Do not disassemble, pressurize, or deform the Data Carrier, subject it to high temperatures (of 100°C or more), or dispose of it by incineration. Dispose of the Data Carrier as industrial waste.



## **List of ASCII Characters**

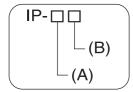
Left digit Right digit	b8 to b5	0000	1001	0010	0011	0100	0101	0110	0111	1000	1101	1010	1011	1100	1101	1110	1111
b4 to b1	Col- umn Row	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0000	0	NUL	TC7(DLE)	(SP)	0	@	Р	`	р								
0001	1	TC <sub>1</sub> (SOH)	DC <sub>1</sub>	!	1	Α	Q	а	q								
0010	2	TC <sub>2</sub> (STX)	DC <sub>2</sub>	II	2	В	R	b	r								
0011	3	TC₃(ETX)	DC <sub>3</sub>	#	3	С	S	С	S								
0100	4	TC <sub>4</sub> (EOT)	DC <sub>4</sub>	\$	4	D	Т	d	t								
0101	5	TC5(NEQ)	TC <sub>8</sub> (NAK)	%	5	Е	U	е	u	ned	ned	ned	ned	ned	peu	ned	Undefined
0110	6	TC <sub>6</sub> (ACK)	TC <sub>9</sub> (SYN)	&	6	F	٧	f	V	Undefined	ıdefi						
0111	7	BEL	TC <sub>10</sub> (ETB)	1	7	G	W	g	w	Š	'n	Š	Š	Ď	ņ	Š	Ď
1000	5	FE <sub>0</sub> (BS)	CAN	(	8	Н	Х	h	х								
1001	9	FE <sub>1</sub> (HT)	EM	)	9	I	Υ	i	у								
1010	10	FE <sub>2</sub> (LF)	SUB	*	:	J	Z	j	z								
1011	11	FE <sub>3</sub> (VT)	ESC	+	;	K	[	k	{								
1100	12	FE4(FF)	IS4(FS)	,	<	L	\	I									
1101	13	FE5(CR)	IS <sub>3</sub> (GS)	-	=	М	]	m	}								
1110	14	so	IS <sub>2</sub> (RS)		>	N	^	n	-								
1111	15	SI	IS <sub>1</sub> (US)	/	?	0	ı	0	DEL								

Note: Do not use the undefined areas.

## **Degree of Protection**

International protection degrees (IP- $\square$ ) are determined by the following tests. Be sure to check the sealing capability under the actual operating environment and conditions before actual use.

•IEC (International Electrotechnical Commission) Standards (IEC60529 November 2001)



Degree of Protection from Solid Materials

Degree		Protection
0	[]	No protection
1	50 mm dia	Protects against penetration of any solid object such as a hand that is 50 mm or more in diameter.
2	12.5 mm di	Protects against penetration of any solid object, such as a finger, that is 12.5 mm or more in diameter.
3	=	Protects against penetration of any solid object, such as a wire, that is 2.5 mm or more in diameter.
4	=====================================	Protects against penetration of any solid object, such as a wire, that is 1 mm or more in diameter.
5		Protects against penetration of dust of a quantity that may cause malfunction or obstruct the safe operation of the product.
6		Protects against penetration of all dust.

**Degree of Protection Against Water** 

Degree	Protection		Test method (with fresh water)	
0	No protection	Not protected against water.	No test	
1	Protection against water drops	Protects against vertical drops of water towards the product.	Water is dropped vertically towards the product from the test machine for 10 min.	1200 mm
2	Protection against water drops	Protects against drops of water approaching at a maximum angle of 15° to the left, right, back, and front of vertical towards the product.	Water is dropped for 2.5 min each (i.e., 10 min in total) towards the product inclined 15° to the left, right, back, and front from the test machine.	15 <sup>2</sup> 1200 mm
3	Protection against sprinkled water	Protects against sprinkled water approaching at a maximum angle of 60° from vertical towards the product.	Water is sprinkled at a maximum angle of 60° to the left and right from vertical for 10 min from the test machine.	Water rate is 0.07 liter/min per hole.

Degree	Protection		Test method (with fresh water)	
4	Protection against water spray	Protects against water spray approaching at any angle towards the product.	Water is sprayed at any angle towards the product for 10 min from the test machine.  Water rate is 0.07 liter/min per hole.	
5	Protection against water jet spray	Protects against water jet spray approaching at any angle towards the product.	Water is jet sprayed at any angle towards the product for 1 min per square meter for at least 3 min in total from the test machine.  Discharging nozzle: 6.3 dia.	
6	Protection against high pressure water jet spray	Protects against high-pressure water jet spray approaching at any angle towards the product.	Water is jet sprayed at any angle towards the product for 1 min per square meter for at least 3 min in total from the test machine.  Discharging nozzle: 12.5 dia.	
7	Protection underwater	Resists the penetration of water when the product is placed underwater at specified pressure for a specified time.	The product is placed 1 m deep in water (if the product is 850 mm max. in height) for 30 min.	
8 (See note.)	Protection underwater	Can be used continuously underwater.	The test method is determined by the manufacturer and user.	

Note: OMRON Test Method

Usage condition: 10 m or less under water in natural conditions

- 1. No water ingress after 1 hour under water at 2 atmospheres of pressure.
- 2. Sensing distance and insulation resistance specifications must be met after 100 repetitions of half hour in 5°C water and half hour in 85°C water.

#### About IPX9K

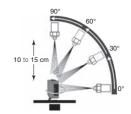
IPX9K is a protection standard regarding high temperature and high-pressure water which is defined by the German standard (DIN 40050 PART9).

Water is sprayed on 80  $^{\circ}$ C hot water with the water pressure of 80 to 100BAR from a nozzle to the test piece.

Amount of water is 14 to 16 liters/minute.

The distance between the test piece and a nozzle is 10 to 15 cm, and the directions of water-drainage are 0 degrees, 30 degrees, 60 degrees, and 90 degrees horizontally.

They are evaluated with the test piece is rotating on a horizontal plane by 30 seconds in each direction.



### •Oil resistance (OMRON in-house standard)

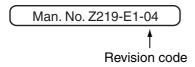
`	,
	Protection
Oil-resistant	No adverse affect from oil drops or oil spray approaching from any direction.
Oil-proof	Protects against penetration of oil drops or oil spray approaching from any direction.

Note. Oil resistance has been tested using a specific oil as defined in the OMRON test method. (JIS C 0920:2003, Appendix 1)

MEMO

## **Revision History**

A manual revision code appears as a suffix to the catalog number at the bottom of the front and rear pages.



Revision code	Date	Revised contents	
01	February 2005	Original production	
02	September 2008	Added information on installing the USB driver for Vista.  Added information on V600-CH1D-V2, V600-A22, and V600-D8KF04.	
02A	April 2014	Added information on V600-CH1D-PSI.  Deleted information about the Regulations and Standards. and made other minor corrections.	
03	March 2015	Changed the type of Hand-held Terminal manufactured by Zebra Technologies, Inc.	
04	September 2016	Minor corrections.	

**Industrial Automation Company OMRON Corporation** 

Tokyo, JAPAN

Contact: www.ia.omron.com

Regional Headquarters OMRON EUROPE B.V. Wegalaan 67-69, 2132 JD Hoofddorp

The Netherlands Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ASIA PACIFIC PTE. LTD. No. 438A Alexandra Road # 05-05/08 (Lobby 2), Alexandra Technopark, Singapore 119967 Tel: (65) 6835-3011/Fax: (65) 6835-2711

OMRON ELECTRONICS LLC 2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON (CHINA) CO., LTD.
Room 2211, Bank of China Tower,
200 Yin Cheng Zhong Road,
PuDong New Area, Shanghai, 200120, China
Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200

**Authorized Distributor:** 

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